



E-Vision Laser 7500, 8500, 10K & 4K Series
HIGHlite Laser 3D II & 4K Series
M-Vision Laser 18K Series
E-Vision 6900 Series
Mercury Quad Series
INSIGHT Dual Laser 4K Series
INSIGHT 4K Quad & Dual LED Series
INSIGHT 4K Laser Series

► PROTOCOL GUIDES

About This Document

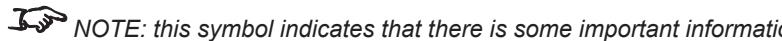
Follow the instructions in this guide carefully to ensure safe and long-lasting use of the projector.

Notes

Symbols used in this guide

Notes

Many pages in this document have a dedicated area for notes. The information in that area is accompanied by the following symbol:



NOTE: this symbol indicates that there is some important information that you should read.

Product badges

Product badges are sometimes used to identify information that only applies to specific projectors as opposed to all projectors covered within the section.

Product revision

Because we at Digital Projection continually strive to improve our products, we may change specifications and designs, and add new features without prior notice.

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E-Vision Laser 7500 & 8500 Series
E-Vision Laser 10K Series
E-Vision Laser 4K Series
High Brightness Digital Video Projector
► PROTOCOL GUIDE



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Introduction

The projector can be controlled by using an external control system or a PC via an RS232 or LAN interface, using a terminal-emulation program.

Network setup

1. Connect the projector to a LAN network.
2. Open the **Setup > Network** menu and edit network settings. The default IP address is **192.168.0.100** and the TCP port number is **7000**.

Serial Port setup

- Baud rate 9,600 bps
- Data length 8 bits
- Stop bits one
- Parity none
- Flow control none

Notes

 For details on connecting the projector to an RS232 or LAN network, or changing network settings, see the user manual.

 Only one control path at a time should be used for protocol control. Attempts to send commands to both serial and network ports at the same time may result in unpredictable behavior.

Protocol commands

Commands are used to simulate menu operations and determine the settings of the projector, and use the following format:

- All commands consist of ASCII text strings starting with an asterisk* and ending with an ASCII Carriage Return character ↵ (code 13):
*command operator <value>↵
- The <command> string determines which setting the command will affect.
- Spaces are required before the operator and before the value.
- The <operator> string can take one of the following formats:

Command type	<operator>	Description
Set	= <value>	Makes the setting take the <value>.
Get	?	Asks what the current value is. The value is returned as an ASCII text string.
Execute		Performs an action. No operator is entered for this type of command.

Notes

 To set the default value of a command, simply enter the command name and ↵, without an operator. For example *orientation↵ will set the orientation to 0 (Desktop Front).

 You must wait for the complete response to a command before sending another command.

Examples

- *orientation = 3↵ sets the orientation to Rear Ceiling (for a ceiling mounted projector positioned behind the screen)
- *aspect.ratio ?↵ asks what the current aspect ratio is
- *zoom.in↵ commands the projector to zoom in
- *orientation=3↵ is an invalid instruction because of the missing spaces before the operator and the value

Responses

If the command has been successful, the projector response begins with ACK or ack ("acknowledged"). For example, if the command is *aspect.ratio = 1↵, the projector will return ACK aspect.ratio = 1↵ or ack aspect.ratio = 1↵, depending on the model. In either case the projector will then change the aspect ratio accordingly.

If the command has not been acknowledged, due to a syntax error or another problem, the projector response will be NAK or nack, followed by a brief description of the problem.

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Input									
input	●	●	×	×	×	0 = HDMI 1 1 = HDMI 2 2 = VGA 3 = COMP 4 = DVI 5 = DisplayPort 6 = HDBaseT 7 = 3G-SDI	0 = DisplayPort 1 = HDMI 1 2 = HDMI 2 3 = HDBaseT 4 = 3G-SDI 5 = HDMI 3 6 = HDMI 4		
Test Pattern									
test.pattern	●	●	×	×	×	0= Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Checkerboard 7 = Crosshatch 8 = V Burst 9 = H Burst 10 = Color Bar 11 = Plunge	0 = Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Cyan 7 = Yellow 8 = Magenta		

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Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
Lens								
zoom.in	X	X	X	X	●	✓	✓	✓
zoom.out	X	X	X	X	●	✓	✓	✓
focus.near	X	X	X	X	●	✓	✓	✓
focus.far	X	X	X	X	●	✓	✓	✓
lens.up	X	X	X	X	●	✓	✓	✓
lens.down	X	X	X	X	●	✓	✓	✓
lens.left	X	X	X	X	●	✓	✓	✓
lens.right	X	X	X	X	●	✓	✓	✓
lens.center	X	X	X	X	●	✓	✓	✓
lens.load	●	X	X	X	X	1 to 10 (integer)		
lens.save	●	●	X	X	X	1 to 10 (integer)		
lens.clear	●	X	X	X	X	1 to 10 (integer)		
lens.type	●	●	X	X	X	0 = non-UST Lens 1 = UST Lens		
lens.lock	●	●	X	X	X	0 = Off 1 = On		

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Notes



Lens commands only work if the projector is switched on.



To use lens commands, make sure the lens is unlocked. If lens.lock is set to 1, most other lens commands are disabled.

Exceptions are lens.type, lens.save and lens.clear.



When used with a get operator, the lens.save command returns a string of zeroes and ones where each zero is an empty memory slot and each one is an occupied slot.

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Image									
pic.mode	●	●	✗	✗	✗	0 = High Bright 1 = Presentation 2 = Video			
db.on	●	●	✗	✗	✗	0 = Off 1 = On			
gamma	●	●	✗	✗	✗	0 = 1.0 1 = 1.8 2 = 2.0 3 = 2.2 4 = 2.35 5 = 2.5 6 = S-curve 7 = DICOM			
brightness	●	●	●	●	✗	0 to 200 (integer)			
contrast	●	●	●	●	✗	0 to 200 (integer)			
saturation	●	●	●	●	✗	0 to 200 (integer)			
hue	●	●	●	●	✗	0 to 200 (integer)			
sharpness	●	●	●	●	✗	0 to 15 (integer)	0 to 20 (integer)		

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- ☞ The values you set of pic.mode, gamma, brightness, contrast, saturation **and hue will only apply to the current image source.**
- ☞ db.on **is not available in 3D.**
- ☞ db.on **cannot be used when edge blending.**

Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
nr.level	●	●	✗	✗	✗	n/a	0 to 3 (integer)	n/a
nr.temporal	●	●	●	●	✗	0 to 3 (integer)	n/a	n/a
nr.block	●	●	●	●	✗	0 to 3 (integer)	n/a	n/a
nr.mosquito	●	●	●	●	✗	0 to 3 (integer)	n/a	n/a
nr.hori	●	●	●	●	✗	0 to 3 (integer)	n/a	n/a
nr.vert	●	●	●	●	✗	0 to 3 (integer)	n/a	n/a
nr.reset	●	●	✗	✗	✗	0 to 3 (integer)	n/a	n/a
h.position	●	●	●	●	✗	0 to 200 (integer)	n/a	n/a
v.position	●	●	●	●	✗	0 to 200 (integer)	n/a	n/a
vga.phase	●	●	●	●	✗	0 to 31 (integer)	n/a	n/a
tracking	●	●	●	●	✗	0 to 200 (integer)	n/a	n/a
sync.level	●	●	●	●	✗	0 to 200 (integer)	n/a	n/a
freeze	●	●	✗	✗	✗	0 = Off 1 = On	n/a	n/a
resync	✗	✗	✗	✗	●	✓	✓	✓

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Notes



The commands on this page will only apply to the current image source.



The vga.phase command is identical to the **Phase** setting in the **Image > Position and Phase** menu.

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Color									
color.space	●	●	✗	✗	✗	0 = Auto 1 = YPbPr 2 = YCbCr 3 = RGB-PC 4 = RGB-Video			
color.temp	●	●	✗	✗	✗	0 = 3200K 1 = 5400K 2 = 6500K 3 = 7500K 4 = 9300K 5 = Native			
color.mode	●	●	✗	✗	✗	0 = ColorMax 1 = Manual Color Matching 2 = Color Temperature 3 = Gains and Lifts			
color.max	●	●	✗	✗	✗	n/a	0 = HDTV (REC709) 1 = Peak 2 = User 1 3 = User 2		

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K		
red.lift	●	●	●	●	×	0 to 200 (integer)				
green.lift	●	●	●	●	×	0 to 200 (integer)				
blue.lift	●	●	●	●	×	0 to 200 (integer)				
red.gain	●	●	●	●	×	0 to 200 (integer)				
green.gain	●	●	●	●	×	0 to 200 (integer)				
blue.gain	●	●	●	●	×	0 to 200 (integer)				
gainlift.reset	✗	✗	✗	✗	●	✓	✓	n/a		
auto.test.ptrn	●	●	✗	✗	✗	0 = Off 1 = On				
user.std.rx	●	●	✗	✗	✗	550 to 750 (integer)				
user.std.ry	●	●	✗	✗	✗	250 to 450 (integer)				
user.std.gx	●	●	✗	✗	✗	200 to 400 (integer)				
user.std gy	●	●	✗	✗	✗	400 to 750 (integer)				
user.std.bx	●	●	✗	✗	✗	50 to 250 (integer)				
user.std.by	●	●	✗	✗	✗	0 to 120 (integer)				
user.std.wx	●	●	✗	✗	✗	200 to 400 (integer)				
user.std.wy	●	●	✗	✗	✗	250 to 450 (integer)				
user.std.reset	✗	✗	✗	✗	●	✓	✓	✓		

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The user.std commands are identical to the settings in the **Setup > ColorMax > Measured Data** menu. Protocol values are multiples of 1000.

Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
user.target.rx	●	●	✗	✗	✗	550 to 750 (integer)		
user.target.ry	●	●	✗	✗	✗	250 to 450 (integer)		
user.target.gx	●	●	✗	✗	✗	200 to 400 (integer)		
user.target gy	●	●	✗	✗	✗	400 to 750 (integer)		
user.target.bx	●	●	✗	✗	✗	50 to 250 (integer)		
user.target.by	●	●	✗	✗	✗	0 to 120 (integer)		
user.target.wx	●	●	✗	✗	✗	200 to 400 (integer)		
user.target.wy	●	●	✗	✗	✗	250 to 450 (integer)		
user.target.cx	●	●	✗	✗	✗	125 to 325 (integer)		
user.target.cy	●	●	✗	✗	✗	225 to 425 (integer)		
user.target.mx	●	●	✗	✗	✗	200 to 400 (integer)		
user.target.my	●	●	✗	✗	✗	50 to 250 (integer)		
user.target.yx	●	●	✗	✗	✗	300 to 500 (integer)		
user.target.yy	●	●	✗	✗	✗	400 to 600 (integer)		
user.target.reset	✗	✗	✗	✗	●	✓	✓	✓

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Notes



The user.target commands are identical to the settings in the **Setup > ColorMax > Target Data — User 1** menu. Protocol values are multiples of 1000.

Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
user2.target.rx	●	●	✗	✗	✗	550 to 750 (integer)		
user2.target.ry	●	●	✗	✗	✗	250 to 450 (integer)		
user2.target.gx	●	●	✗	✗	✗	200 to 400 (integer)		
user2.target gy	●	●	✗	✗	✗	400 to 750 (integer)		
user2.target.bx	●	●	✗	✗	✗	50 to 250 (integer)		
user2.target.by	●	●	✗	✗	✗	0 to 120 (integer)		
user2.target.wx	●	●	✗	✗	✗	200 to 400 (integer)		
user2.target.wy	●	●	✗	✗	✗	250 to 450 (integer)		
user2.target.cx	●	●	✗	✗	✗	125 to 325 (integer)		
user2.target.cy	●	●	✗	✗	✗	225 to 425 (integer)		
user2.target.mx	●	●	✗	✗	✗	200 to 400 (integer)		
user2.target.my	●	●	✗	✗	✗	50 to 250 (integer)		
user2.target.yx	●	●	✗	✗	✗	300 to 500 (integer)		
user2.target.yy	●	●	✗	✗	✗	400 to 600 (integer)		
user2.target.reset	✗	✗	✗	✗	●	✓	✓	✓
user.p7.rst	✗	✗	✗	✗	●	✓	✓	n/a

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Notes



The user2.target commands are identical to the settings in the Setup > ColorMax > Target Data — User 2 menu. Protocol values are multiples of 1000.

Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
hsg.hue.r	●	●	●	●	✗	0 to 200 (integer)		
hsg.hue.g	●	●	●	●	✗	0 to 200 (integer)		
hsg.hue.b	●	●	●	●	✗	0 to 200 (integer)		
hsg.hue.c	●	●	●	●	✗	0 to 200 (integer)		
hsg.hue.m	●	●	●	●	✗	0 to 200 (integer)		
hsg.hue.y	●	●	●	●	✗	0 to 200 (integer)		
hsg.sat.r	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	
hsg.sat.g	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	
hsg.sat.b	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	
hsg.sat.c	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	
hsg.sat.m	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	
hsg.sat.y	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	

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Notes



The hsg commands are identical to the settings in the **Color > Manual Color Matching** menu.

Command	Operators allowed						Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
hsg.gain.r	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.gain.g	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.gain.b	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.gain.c	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.gain.m	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.gain.y	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.white.r	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.white.g	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.white.b	●	●	●	●	X		0 to 200 (integer)	0 to 100 (integer)	
hsg.reset	X	X	X	X	●	✓	✓	✓	✓

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Notes



The hsg commands are identical to the settings in the **Color > Manual Color Matching** menu.

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Geometry									
aspect.ratio	●	●	✗	✗	✗	0 = 5:4 1 = 4:3 2 = 16:10 3 = 16:9 4 = 1.88 5 = 2.35 6 = Theaterscope 7 = Source 8 = Unscaled			
digi.zoom	●	●	✗	✗	✗	0 to 100 (integer)			
digi.pan	●	●	✗	✗	✗	-320 to +320 (integer)			
digi.pan.bound	✗	●	✗	✗	✗	-320 to +320 (integer)			
digi.scan	●	●	✗	✗	✗	-200 to +200 (integer)			
digi.scan.bound	✗	●	✗	✗	✗	-200 to +200 (integer)			
digi.zoom.rst	✗	✗	✗	✗	●	✓	✓	✓	
overscan	●	●	✗	✗	✗	0 = Off 1 = Crop 2 = Zoom			
h.keystone	●	●	●	●	✗	-600 to +600 (integer)			
v.keystone	●	●	●	●	✗	-400 to +400 (integer)			
keystone.reset	✗	✗	✗	✗	●	n/a	✓		
rotation	●	●	●	●	✗	-100 to +100 (integer)			
rotation.reset	✗	✗	✗	✗	●	n/a	✓		

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
h.pin.barrel	●	●	●	●	×	-	-150 to +300 (integer)			
v.pin.barrel	●	●	●	●	×	-	-150 to +300 (integer)			
pin.barrel.reset	✗	✗	✗	✗	●	n/a			✓	
4corner.ulx	●	●	●	●	×	-	-192 to +192 (integer)			
4corner.uly	●	●	●	●	×	-	-120 to +120 (integer)			
4corner.urx	●	●	●	●	×	-	-192 to +192 (integer)			
4corner.ury	●	●	●	●	×	-	-120 to +120 (integer)			
4corner.llx	●	●	●	●	×	-	-192 to +192 (integer)			
4corner.lly	●	●	●	●	×	-	-120 to +120 (integer)			
4corner.lrx	●	●	●	●	×	-	-192 to +192 (integer)			
4corner.lry	●	●	●	●	×	-	-120 to +120 (integer)			
4corner.reset	✗	✗	✗	✗	●	n/a			✓	

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Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
arc.top	●	●	●	●	✗	-150 to +150 (integer)	n/a		
arc.bottom	●	●	●	●	✗	-150 to +150 (integer)	n/a		
arc.left	●	●	●	●	✗	-150 to +150 (integer)	n/a		
arc.right	●	●	●	●	✗	-150 to +150 (integer)	n/a		
arc.t	●	●	✗	✗	✗	n/a		-192 to +192 (integer)	
arc.b	●	●	✗	✗	✗	n/a		-120 to +120 (integer)	
arc.l	●	●	✗	✗	✗	n/a		-192 to +192 (integer)	
arc.r	●	●	✗	✗	✗	n/a		-120 to +120 (integer)	
arc.reset	✗	✗	✗	✗	●	n/a		✓	
blanking.top	●	●	●	●	✗	0 to 360 (integer)			
blanking.bottom	●	●	●	●	✗	0 to 360 (integer)			
blanking.left	●	●	●	●	✗	0 to 534 (integer)			
blanking.right	●	●	●	●	✗	0 to 534 (integer)			
blanking.reset	✗	✗	✗	✗	●	✓	✓	✓	

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
warp.reset	X	X	X	X	●	✓		✓	✓	
active.warp	●	●	X	X	X	0 = none (no warp function is set) 1 = Keystone 2 = Four Corner 3 = Rotation 4 = Pin/Barrel 5 = Arc		0 = none (no warp function is set) 1 = Keystone 2 = Four Corner 3 = Rotation 4 = Pin/Barrel		
cust.wp.write	●	X	X	X	X	1 = User 1 file 2 = User 2 file		n/a		
cust.wp.clear	●	X	X	X	X	1 = User 1 file 2 = User 2 file		n/a		
cust.wp.send	●	●	X	X	X	0 = custom warp transfer mode off 1 = custom warp transfer User 1 file 2 = custom warp transfer User 2 file		n/a		
cust.wp.ck.sum	X	●	X	X	X	Returns the unsigned 32 bits check sum by summing all bytes in the current sent warp file when <code>cust.wp.send</code> is not zero		n/a		
warp.cust	●	●	X	X	X	0 = Off 1 = User 1 2 = User 2				

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Edge Blend										
eb.stat	●	●	✗	✗	✗	0 = Off 1 = On				
eb.adl	●	●	✗	✗	✗	0 = Off 1 = On				
eb.top	●	●	●	●	✗	0, 100 to 500				
eb.bottom	●	●	●	●	✗	0, 100 to 500				
eb.left	●	●	●	●	✗	0, 100 to 500				
eb.right	●	●	●	●	✗	0, 100 to 500				
eb.blu.top	●	●	●	●	✗	0 to 32 (integer)				
eb.blu.btm	●	●	●	●	✗	0 to 32 (integer)	n/a			
eb.blu.bottom	●	●	●	●	✗	n/a	0 to 32 (integer)			
eb.blu.left	●	●	●	●	✗	0 to 32 (integer)				
eb.blu.right	●	●	●	●	✗	0 to 32 (integer)				
eb.all	●	●	✗	✗	✗	n/a	0 to 32 (integer)			
eb.red	●	●	✗	✗	✗	0 to 255 (integer)	0 to 32 (integer)			
eb.green	●	●	✗	✗	✗	0 to 255 (integer)	0 to 32 (integer)			
eb.blue	●	●	✗	✗	✗	0 to 255 (integer)	0 to 32 (integer)			
eb.reset	✗	✗	✗	✗	●	✓	✓	✓		

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K
3D								
3d.format	●	●	✗	✗	✗	0 = Off 1 = Auto 2 = Side-By-Side (Half) 3 = Top-And-Bottom 4 = Dual-Pipe 5 = Frame Sequential	0 = Off 1 = Auto 2 = Dual-Pipe 3 = Frame Sequential	
3d.dlplink	●	●	✗	✗	✗	0 = Off 1 = On		
3d.dominance	●	●	✗	✗	✗	0 = Normal 1 = Reverse		
3d.darktime	●	●	✗	✗	✗	0 = 0.65 ms 1 = 1.3 ms 2 = 1.95 ms		
3d.syncoffset	●	●	✗	✗	✗	0 to 60 (integer)		
3d.syncref	✗	●	✗	✗	✗	0 = Internal 1 = External		
Laser								
laser.mode	●	●	✗	✗	✗	0 = Eco 1 = Normal 2 = Custom		
laser.power	●	●	✗	✗	✗	20-100 (20%-100% power level; only available when laser.mode=2)		
laser.hours	✗	●	✗	✗	✗	integer		

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Notes



laser.power is only effective if laser.mode is set to custom.

Command	Operators allowed		Values accepted / Format of response – per model					Notes	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Setup									
altitude	●	●	✗	✗	✗	1 = On 2 = Auto 3 = Quiet	0 = reserved for other applications 1 = On 2 = Auto 3 = Quiet		
cooling.condition	●	●	✗	✗	✗	0 = Table 1 = Ceiling 2 = Freetilt 3 = Auto			
orientation	●	●	✗	✗	✗	0 = Desktop Front 1 = Ceiling Front 2 = Desktop Rear 3 = Ceiling Rear 4 = Auto-front			
screen.setting	●	●	✗	✗	✗	0 = 16:10 1 = 16:9 2 = 4:3			
auto.poweroff	●	●	✗	✗	✗	0 = Off 1 = On			
auto.poweron	●	●	✗	✗	✗	0 = Off 1 = On			

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
schedule.power	●	●	✗	✗	✗	0 = Off 1 = On			
schedule1.on.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule1.off.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule1.on.time	●	●	✗	✗	✗	HH:MM			
schedule1.off.time	●	●	✗	✗	✗	HH:MM			
schedule2.on.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule2.off.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule2.on.time	●	●	✗	✗	✗	HH:MM			
schedule2.off.time	●	●	✗	✗	✗	HH:MM			
date	●	●	✗	✗	✗	yyyy/MM/dd	DD:MM:YYYY		
time.zone	●	●	✗	✗	✗	-11 to +12 (integer)			
time.adjust	●	●	✗	✗	✗	HH:MM			
startup.logo	●	●	✗	✗	✗	0 = Off 1 = On			
blank.screen	●	●	✗	✗	✗	0 = Logo 1 = Black 2 = Blue 3 = White			

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K		
trig.1	●	●	✗	✗	✗	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off				
trig.2	●	●	✗	✗	✗	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off				
auto.source	●	●	✗	✗	✗	0 = Off 1 = On				
ir.enable	●	●	✗	✗	✗	0 = Off (Disable) 1 = On (Enable)				

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
ir.code	●	●	✗	✗	✗	00 to 99			
ir.code.rst	✗	✗	✗	✗	●	✓	✓	✓	
osd.lang	●	●	✗	✗	✗	0 = English 1 = French 2 = German 3 = Spanish 4 = Simplified Chinese			
osd.menupos	●	●	✗	✗	✗	0 = Top Left 1 = Top Right 2 = Bottom Left 3 = Bottom Right 4 = Center			
osd.trans	●	●	✗	✗	✗	0 = 0% 1 = 25% 2 = 50% 3 = 75%			
osd.timer	●	●	✗	✗	✗	0 = Always On 1 = 10 Seconds 2 = 30 Seconds 3 = 60 Seconds			
osd.msgbox	●	●	✗	✗	✗	0 = Off 1 = On	n/a		
recall.mem	●	●	✗	✗	✗	0 = Preset A 1 = Preset B 2 = Preset C 3 = Preset D 4 = Default			
save.mem	●	●	✗	✗	✗	0 = Preset A 1 = Preset B 2 = Preset C 3 = Preset D			

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Network										
network.mode	●	●	✗	✗	✗	0 = Projector Control 1 = Service		n/a		
standby.power						n/a		0 = Save 1 = Eco 2 = Normal		
lan.power	●	●	✗	✗	✗	0 = Off 1 = On		n/a		
lan.dhcp	●	●	✗	✗	✗	0 = Off 1 = On				
lan.ip	●	●	✗	✗	✗	A valid IP address in the following format: xxx.xxx.xxx.xxx				
lan.subnet	●	●	✗	✗	✗	A valid subnet address in the following format: xxx.xxx.xxx.xxx				
lan.gateway	●	●	✗	✗	✗	A valid gateway address in the following format: xxx.xxx.xxx.xxx				
lan.dns	●	●	✗	✗	✗	A valid DNS address in the following format: xxx.xxx.xxx.xxx				
lan.mac	●	●	✗	✗	✗	string				
lan.amx	●	●	✗	✗	✗	0 = Off 1 = On				

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
PIP									
pip.mode	●	●	✗	✗	✗	0 = Off 1 = On			
pip.input	●	●	✗	✗	✗	0 = HDMI 1 1 = HDMI 2 2 = RGB (VGA) 3 = COMP 4 = DisplayPort 5 = HDBaseT 6 = 3G-SDI	0 = DisplayPort 1 = HDMI 1 2 = HDMI 2 3 = HDBaseT 4 = 3G-SDI		
pip.position	●	●	✗	✗	✗	0 = TopLeft 1 = TopRight 2 = BottomLeft 3 = BottomRight 4 = PBP			
pip.swap	✗	✗	✗	✗	●	✓	✓	✓	
Information									
model.name	✗	●	✗	✗	✗	string			
serial	✗	●	✗	✗	✗	string			
sw.version	✗	●	✗	✗	✗	string			
sw1.version	✗	●	✗	✗	✗	string			
sw2.version	✗	●	✗	✗	✗	string			
sw3.version	✗	●	✗	✗	✗	string			
act.source	✗	●	✗	✗	✗	string			
signal	✗	●	✗	✗	✗	string			

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
h.refresh	X	●	X	X	X	number			
v.refresh	X	●	X	X	X	number			
pixel.clock	X	●	X	X	X	number			
laser.hours	X	●	X	X	X	integer			
atmos.alti	X	●	X	X	X	number			
atmos.pressure	X	●	X	X	X	number			
ac.voltage	X	●	X	X	X	0 = 90~150 1 = 160~264			
g.ceiling	X	●	X	X	X	0 = table 1 = ceiling			
g.portrait	X	●	X	X	X	number			
g.tilt	X	●	X	X	X	number			
altitude.info	X	●	X	X	X	0 = Low 1 = High	0 = SEA-1 1 = SEA-2 2 = MODE-1 3 = MODE-2 4 = MODE-3	0 = Low 1 = High	
laser.power.info	X	●	X	X	X	number			

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
ti	X	●	X	X	X		number			
ti2	X	●	X	X	X		number			
tc	X	●	X	X	X		number			
tb1	X	●	X	X	X		number			
tb2	X	●	X	X	X		number			
fan1_3	X	●	X	X	X		xxxx / xxxx / xxxx (speed of FAN 1~3)	n/a		
fan4_6	X	●	X	X	X		xxxx / xxxx / xxxx (speed of FAN 4~6)	n/a		
fan7_9	X	●	X	X	X		xxxx / xxxx / xxxx (speed of FAN 7~9)	n/a		
fan10_12	X	●	X	X	X		xxxx / xxxx / xxxx (speed of FAN 10~12)	n/a		
fan13_15	X	●	X	X	X		xxxx / xxxx / xxxx (speed of FAN 13~15)	n/a		
fan16_18	X	●	X	X	X		xxxx / NA / NA (speed of FAN 16)	n/a		
fans	X	●	X	X	X		All fan & environment status			
water.pump	X	●	X	X	X		number			
factory.reset	X	X	X	X	●	✓	✓	✓	✓	

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
Miscellaneous										
power	●	●	✗	✗	✗	0 = Off 1 = On				
shutter	●	●	✗	✗	✗	0 = Open 1 = Close				
total.hours	✗	●	✗	✗	✗	integer				
total.minutes	✗	●	✗	✗	✗	n/a	number			
laser.minutes	✗	●	✗	✗	✗	n/a	number			
laser.normal.hr	✗	●	✗	✗	✗	n/a	number			
laser.normal.min	✗	●	✗	✗	✗	n/a	number			
laser.eco.hr	✗	●	✗	✗	✗	n/a	number			
laser.eco.min	✗	●	✗	✗	✗	n/a	number			
laser.reset						n/a		✓		
status	✗	●	✗	✗	✗	0 = Standby 1 = Warm Up 2 = Imaging 3 = Cooling 4 = Error				
errcode	✗	●	✗	✗	✗	string				
cw.index	●	●	✗	✗	✗	n/a	0, 100 to 1000			
pw.index	●	●	✗	✗	✗	n/a	0, 100 to 1000			

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision Laser 7500 & 8500	E-Vision Laser 10K	E-Vision Laser 4K	
dlp.pattern	●	✗	✗	✗	✗	n/a			0 = Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Cyan 7 = Magenta 8 = Yellow 9 = Checkboard 10 = Vramp 11 = Hramp 12 = Grid 13 = Cross, 14 = FPGA_TP_Calibration	
pri.reset	✗	✗	✗	✗	●	n/a			✓	
mfg.reset	✗	✗	✗	✗	●	n/a			✓	
sp.index	●	●	✗	✗	✗	n/a			0, 0 to 4096	
sp.index.v sp.index.h	●	●	✗	✗	✗	n/a			0, 0 to 4096	
sp.t1	●	●	✗	✗	✗	n/a			0, 0 to 4096	
sp.t2	●	●	✗	✗	✗	n/a			0, 0 to 4096	
psoc4.ver	✗	●	✗	✗	✗	n/a			string	
warp.key	✗	●	✗	✗	✗	n/a			0 = licence fail, timeout expired 1 = licence pass, timeout expired 2 = licence fail, timeout not expired 3 = licence pass, timeout not expired	



HIGHlite Laser II 3D Series

HIGHlite Laser 4K Series

M-Vision Laser 18K Series

High Brightness Digital Video Projector

► PROTOCOL GUIDE



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Introduction

The projector can be controlled by using an external control system or a PC via an RS232 or LAN interface, using a terminal-emulation program.

Network setup

1. Connect the projector to a LAN network.
2. Open the **Setup > Network** menu and edit network settings. The default IP address is **192.168.0.100** and the TCP port number is **7000**.

Serial Port setup

- Baud rate 9,600 bps
- Data length 8 bits
- Stop bits one
- Parity none
- Flow control none

Notes

 For details on connecting the projector to an RS232 or LAN network, or changing network settings, see the user manual.

 Only one control path at a time should be used for protocol control. Attempts to send commands to both serial and network ports at the same time may result in unpredictable behavior.

Protocol commands

Commands are used to simulate menu operations and determine the settings of the projector, and use the following format:

- All commands consist of ASCII text strings starting with an asterisk* and ending with an ASCII Carriage Return character ↴ (code 13):
*command operator <value>↵
- The <command> string determines which setting the command will affect.
- Spaces are required before the operator and before the value.
- The <operator> string can take one of the following formats:

Command type	<operator>	Description
Set	= <value>	Makes the setting take the <value>.
Get	?	Asks what the current value is. The value is returned as an ASCII text string.
Execute		Performs an action. No operator is entered for this type of command.

Notes

 To set the default value of a command, simply enter the command name and ↴, without an operator. For example *orientation ↴ will set the orientation to 0 (Desktop Front).

 You must wait for the complete response to a command before sending another command.

Examples

- *orientation = 3↵ sets the orientation to Rear Ceiling (for a ceiling mounted projector positioned behind the screen)
 *aspect.ratio ?↵ asks what the current aspect ratio is
 *zoom.in↵ commands the projector to zoom in
 *orientation=3↵ is an invalid instruction because of the missing spaces before the operator and the value

Responses

If the command has been successful, the projector response begins with ACK or ack ("acknowledged"). For example, if the command is *aspect.ratio = 1↵, the projector will return ACK aspect.ratio = 1↵ or ack aspect.ratio = 1↵, depending on the model. In either case the projector will then change the aspect ratio accordingly.

If the command has not been acknowledged, due to a syntax error or another problem, the projector response will be NAK or nack, followed by a brief description of the problem.

Command	Operators allowed		Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	
			HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
Input						
input	●	●	✗	✗	✗	<p>0= HDMI1 1= HDMI2 2= RGB 3= BNC 4= DVI 5= DP 6= HDBT 7= HDSDI</p> <p>0 = DisplayPort 1 = HDMI 1 2 = HDMI 2 3 = HDBaseT 4 = 3G-SDI</p> <p>0 = HDMI 1 1 = HDMI 2 2 = DisplayPort 1 3 = DisplayPort 2 4 = HDBaseT 5 = 3G-SDI</p>
Test Pattern						
test.pattern	●	●	✗	✗	✗	<p>0= Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Checkerboard 7 = Crosshatch 8 = V Burst 9 = H Burst 10 = Color Bar 11 = Plunge</p> <p>0 = Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Cyan 7 = Yellow 8 = Magenta</p> <p>0= Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Checkerboard 7 = Crosshatch 8 = V Burst 9 = H Burst 10 = Color Bar 11 = Plunge</p>

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Command	Operators allowed						Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K
Lens									
zoom.in	X	X	X	X	●	✓	✓	✓	
zoom.out	X	X	X	X	●	✓	✓	✓	
focus.near	X	X	X	X	●	✓	✓	✓	
focus.far	X	X	X	X	●	✓	✓	✓	
lens.up	X	X	X	X	●	✓	✓	✓	
lens.down	X	X	X	X	●	✓	✓	✓	
lens.left	X	X	X	X	●	✓	✓	✓	
lens.right	X	X	X	X	●	✓	✓	✓	
lens.center	X	X	X	X	●	✓	✓	✓	
lens.load	●	X	X	X	X	n/a	1 to 10 (integer)		
lens.save	●	●	X	X	X	n/a	1 to 10 (integer)		
lens.clear	●	X	X	X	X	n/a	1 to 10 (integer)		
lens.type	●	●	X	X	X	n/a	1 to 10 (integer)	n/a	
lens.lock	●	●	X	X	X	n/a	0 = Off 1 = On		

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Notes



Lens commands only work if the projector is switched on.



To use any lens commands except lens.type, make sure the lens is unlocked. If lens.lock is set to 1, most other lens commands are disabled.



When used with a get operator, the lens.save command returns a string of zeroes and ones where each zero is an empty memory slot and each one is an occupied slot.

Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K
Image								
pic.mode	●	●	✗	✗	✗	0 = High Bright 1 = Presentation 2 = Video	n/a	0 = High Bright 1 = Presentation 2 = Video
db.on	●	●	✗	✗	✗	0 = Off 1 = On		
sp.on	●	●	✗	✗	✗	n/a	0 = Off 1 = On	n/a
gamma	●	●	✗	✗	✗	0 = 1.0 1 = 1.8 2 = 2.0 3 = 2.2 4 = 2.35 5 = 2.5 6 = S-Curve 7 = DICOM 8 = HDR PQ-400 9 = HDR PQ-500 10 = HDR PQ-1000 11 = HDR HLG	0 = 1.0 1 = 1.8 2 = 2.0 3 = 2.2 4 = 2.35 5 = 2.5 6 = S-Curve 7 = DICOM	0 = 1.0 1 = 1.8 2 = 2.0 3 = 2.2 4 = 2.35 5 = 2.5 6 = S-Curve 7 = DICOM
brightness	●	●	●	●	✗	0 to 200 (integer)		
contrast	●	●	●	●	✗	0 to 200 (integer)		
saturation	●	●	●	●	✗	0 to 200 (integer)		
hue	●	●	●	●	✗	0 to 200 (integer)		
sharpness	●	●	●	●	✗	0 to 15 (integer)	0 to 10 (integer)	0 to 15 (integer)

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Notes

 The values you set of pic.mode, gamma, brightness, contrast, saturation *and* hue will only apply to the current image source.

 db.on is not available in 3D.

 db.on cannot be used when edge blending.

Command	Operators allowed						Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K
nr	●	●	✗	✗	✗	n/a	0 to 3 (integer)		
nr.level	●	●	✗	✗	✗	n/a	0 to 3 (integer)	n/a	
nr.temporal	●	●	●	●	✗	0 to 3 (integer)	n/a		
nr.block	●	●	●	●	✗	0 to 3 (integer)	n/a		
nr.mosquito	●	●	●	●	✗	0 to 3 (integer)	n/a		
nr.hori	●	●	●	●	✗	0 to 3 (integer)	n/a		
nr.vert	●	●	●	●	✗	0 to 3 (integer)	n/a		
nr.reset	●	●	✗	✗	✗	0 to 3 (integer)	n/a		
h.position	●	●	●	●	✗	0 to 200 (integer)	n/a		
v.position	●	●	●	●	✗	0 to 200 (integer)	n/a		
vga.phase	●	●	●	●	✗	0 to 31 (integer)	n/a		
tracking	●	●	●	●	✗	0 to 200 (integer)	n/a		
sync.level	●	●	●	●	✗	0 to 200 (integer)	n/a		
freeze	●	●	✗	✗	✗	0 = Off 1 = On			
resync	✗	✗	✗	✗	●	✓	✓	✓	

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Notes

The commands on this page will only apply to the current image source.



The vga.phase command is identical to the Phase setting in the **Image > Position and Phase** menu.

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
Color									
color.space	●	●	✗	✗	✗	0 = Auto 1 = YPbPr 2 = YCbCr 3 = RGB-PC 4 = RGB-Video			
color.temp	●	●	✗	✗	✗	0 = 3200K 1 = 5400K 2 = 6500K 3 = 7500K 4 = 9300K 5 = Native			
color.mode	●	●	✗	✗	✗	0 = ColorMax 1 = Manual Color Matching 2 = Color Temperature 3 = Gains and Lifts			
color.max	●	●	✗	✗	✗	0 = REC709 1 = EBU 2 = SMPTE 3 = Native 4 = User 1 5 = User 2	0 = REC709 1 = EBU 2 = SMPTE 3 = Peak 4 = User 1 5 = User 2	0 = HDTV (REC709) 1 = Peak 2 = User 1 3 = User 2	

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Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
red.lift	●	●	●	●	✗	0 to 200 (integer)			
green.lift	●	●	●	●	✗	0 to 200 (integer)			
blue.lift	●	●	●	●	✗	0 to 200 (integer)			
red.gain	●	●	●	●	✗	0 to 200 (integer)			
green.gain	●	●	●	●	✗	0 to 200 (integer)			
blue.gain	●	●	●	●	✗	0 to 200 (integer)			
gainlift.reset	✗	✗	✗	✗	●	✓	n/a	✓	
auto.test.ptrn	●	●	✗	✗	✗	0 = Off 1 = On			
user.std.rx	●	●	✗	✗	✗	550 to 750 (integer)			
user.std.ry	●	●	✗	✗	✗	250 to 450 (integer)			
user.std.gx	●	●	✗	✗	✗	200 to 400 (integer)			
user.std gy	●	●	✗	✗	✗	400 to 750 (integer)			
user.std.bx	●	●	✗	✗	✗	50 to 250 (integer)			
user.std.by	●	●	✗	✗	✗	0 to 120 (integer)			
user.std.wx	●	●	✗	✗	✗	200 to 400 (integer)			
user.std.wy	●	●	✗	✗	✗	250 to 450 (integer)			
user.std.reset	✗	✗	✗	✗	●	✓	✓	✓	

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The user.std commands are identical to the settings in the **Setup > ColorMax > Measured Data** menu. Protocol values are multiples of 1000.

Command	Operators allowed		Values accepted / Format of response – per model					Notes	
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
user.target.rx	●	●	✗	✗	✗	550 to 750 (integer)			
user.target.ry	●	●	✗	✗	✗	250 to 450 (integer)			
user.target.gx	●	●	✗	✗	✗	200 to 400 (integer)			
user.target gy	●	●	✗	✗	✗	400 to 750 (integer)			
user.target.bx	●	●	✗	✗	✗	50 to 250 (integer)			
user.target by	●	●	✗	✗	✗	0 to 120 (integer)			
user.target.wx	●	●	✗	✗	✗	200 to 400 (integer)			
user.target.wy	●	●	✗	✗	✗	250 to 450 (integer)			
user.target.cx	●	●	✗	✗	✗	125 to 325 (integer)			
user.target.cy	●	●	✗	✗	✗	225 to 425 (integer)			
user.target.mx	●	●	✗	✗	✗	200 to 400 (integer)			
user.target.my	●	●	✗	✗	✗	50 to 250 (integer)			
user.target.yx	●	●	✗	✗	✗	300 to 500 (integer)			
user.target.yy	●	●	✗	✗	✗	400 to 600 (integer)			
user.target.reset	✗	✗	✗	✗	● ✓		✓	✓	

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The user.target commands are identical to the settings in the Setup > ColorMax > Target Data — User 1 menu. Protocol values are multiples of 1000.

Command	Operators allowed		Values accepted / Format of response – per model					Notes	
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
user2.target.rx	●	●	✗	✗	✗	550 to 750 (integer)			
user2.target.ry	●	●	✗	✗	✗	250 to 450 (integer)			
user2.target.gx	●	●	✗	✗	✗	200 to 400 (integer)			
user2.target gy	●	●	✗	✗	✗	400 to 750 (integer)			
user2.target.bx	●	●	✗	✗	✗	50 to 250 (integer)			
user2.target.by	●	●	✗	✗	✗	0 to 120 (integer)			
user2.target.wx	●	●	✗	✗	✗	200 to 400 (integer)			
user2.target.wy	●	●	✗	✗	✗	250 to 450 (integer)			
user2.target.cx	●	●	✗	✗	✗	125 to 325 (integer)			
user2.target.cy	●	●	✗	✗	✗	225 to 425 (integer)			
user2.target.mx	●	●	✗	✗	✗	200 to 400 (integer)			
user2.target.my	●	●	✗	✗	✗	50 to 250 (integer)			
user2.target.yx	●	●	✗	✗	✗	300 to 500 (integer)			
user2.target.yy	●	●	✗	✗	✗	400 to 600 (integer)			
user2.target.reset	✗	✗	✗	✗	● ✓		✓	✓	

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The user2.target commands are identical to the settings in the Setup > ColorMax > Target Data — User 2 menu. Protocol values are multiples of 1000.

Command	Operators allowed						Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K
hsg.hue.r	●	●	●	●	×		0 to 200 (integer)		
hsg.hue.g	●	●	●	●	×		0 to 200 (integer)		
hsg.hue.b	●	●	●	●	×		0 to 200 (integer)		
hsg.hue.c	●	●	●	●	×		0 to 200 (integer)		
hsg.hue.m	●	●	●	●	×		0 to 200 (integer)		
hsg.hue.y	●	●	●	●	×		0 to 200 (integer)		
hsg.sat.r	●	●	●	●	×	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)	
hsg.sat.g	●	●	●	●	×	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)	
hsg.sat.b	●	●	●	●	×	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)	
hsg.sat.c	●	●	●	●	×	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)	
hsg.sat.m	●	●	●	●	×	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)	
hsg.sat.y	●	●	●	●	×	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)	

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Notes



The hsg commands are identical to the settings in the **Color > Manual Color Matching** menu.

Command	Values accepted / Format of response – per model						Notes	
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K
hsg.gain.r	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.gain.g	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.gain.b	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.gain.c	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.gain.m	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.gain.y	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.white.r	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.white.g	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.white.b	●	●	●	●	✗	0 to 200 (integer)	0 to 100 (integer)	0 to 200 (integer)
hsg.reset	✗	✗	✗	✗	●	✓	✓	✓

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The hsg commands are identical to the settings in the **Color > Manual Color Matching** menu.

Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
Geometry										
aspect.ratio	●	●	✗	✗	✗	0 = 5:4 1 = 4:3 2 = 16:10 3 = 16:9 4 = 1.88 5 = 2.35 6 = Theaterscope 7 = Source 8 = Unscaled				
digi.zoom	●	●	✗	✗	✗	0 to 100 (integer)				
digi.pan	●	●	✗	✗	✗	-320 to +320 (integer)				
digi.pan.bound	✗	●	✗	✗	✗	-320 to +320 (integer)				
digi.scan	●	●	✗	✗	✗	-200 to +200 (integer)				
digi.scan.bound	✗	●	✗	✗	✗	-200 to +200 (integer)				
digi.zoom.rst	✗	✗	✗	✗	●	✓	✓	✓		
overscan	●	●	✗	✗	✗	0 = Off 1 = Crop 2 = Zoom				
h.keystone	●	●	●	●	✗		-470 to +470 (integer)	-600 to +600 (integer)		
v.keystone	●	●	●	●	✗		-400 to +400 (integer)	-400 to +400 (integer)		
keystone.reset	✗	✗	✗	✗	●	n/a	✓		n/a	
rotation	●	●	●	●	✗	-100 to +100 (integer)				
rotation.reset	✗	✗	✗	✗	●	n/a	✓		n/a	

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Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
h.pin.barrel	●	●	●	●	×	-150 to +300 (integer)	-120 to +229 (integer)	-150 to +300 (integer)		
v.pin.barrel	●	●	●	●	×	-150 to +300 (integer)	-120 to +120 (integer)	-150 to +300 (integer)		
pin.barrel.reset	×	×	×	×	●	n/a	✓	n/a		
4corner.ulx	●	●	●	●	×	-192 to +192 (integer)				
4corner.uly	●	●	●	●	×	-120 to +120 (integer)				
4corner.urx	●	●	●	●	×	-192 to +192 (integer)				
4corner.ury	●	●	●	●	×	-120 to +120 (integer)				
4corner.llx	●	●	●	●	×	-192 to +192 (integer)				
4corner.lly	●	●	●	●	×	-120 to +120 (integer)				
4corner.lrx	●	●	●	●	×	-192 to +192 (integer)				
4corner.lry	●	●	●	●	×	-120 to +120 (integer)				
4corner.reset	×	×	×	×	●	n/a	✓	n/a		
arc.top	●	●	●	●	×	-150 to +150 (integer)	-60 to +115 (integer)	-150 to +150 (integer)		
arc.bottom	●	●	●	●	×	-150 to +150 (integer)	-60 to +114 (integer)	-150 to +150 (integer)		
arc.left	●	●	●	●	×	-150 to +150 (integer)	-60 to +115 (integer)	-150 to +150 (integer)		
arc.right	●	●	●	●	×	-150 to +150 (integer)	-60 to +114 (integer)	-150 to +150 (integer)		
arc.reset	×	×	×	×	●	n/a	✓	n/a		

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Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
blanking.top	●	●	●	●	✗	0 to 360 (integer)			
blanking.bottom	●	●	●	●	✗	0 to 360 (integer)			
blanking.left	●	●	●	●	✗	0 to 534 (integer)			
blanking.right	●	●	●	●	✗	0 to 534 (integer)			
blanking.reset	✗	✗	✗	✗	●	✓	✓	✓	
warp.reset	✗	✗	✗	✗	●	✓	✓	✓	
active.warp	●	●	✗	✗	✗	0 = none (no warp function is set) 1 = Keystone 2 = Four Corner 3 = Rotation 4 = Pin/Barrel 5 = Arc			
cust.wp.write	●	✗	✗	✗	✗	1 = User 1 file 2 = User 2 file	n/a	1 = User 1 file 2 = User 2 file	
cust.wp.clear	●	✗	✗	✗	✗	1 = User 1 file 2 = User 2 file	n/a	1 = User 1 file 2 = User 2 file	
cust.wp.send	●	●	✗	✗	✗	0 = custom warp transfer mode off 1 = custom warp transfer User 1 file 2 = custom warp transfer User 2 file	n/a	0 = custom warp transfer mode off 1 = custom warp transfer User 1 file 2 = custom warp transfer User 2 file	
cust.wp.ck.sum	✗	●	✗	✗	✗	Returns the unsigned 32 bits check sum by summing all bytes in the current sent warp file when cust.wp.send is not zero	n/a	Returns the unsigned 32 bits check sum by summing all bytes in the current sent warp file when cust.wp.send is not zero	
warp.cust	●	●	✗	✗	✗	0 = Off 1 = User 1 2 = User 2			

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Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
Edge Blend									
eb.stat	●	●	✗	✗	✗	0 = Off 1 = On			
eb.adl	●	●	✗	✗	✗	0 = Off 1 = On			
eb.top	●	●	●	●	✗	0, 100 to 500			
eb.bottom	●	●	●	●	✗	0, 100 to 500			
eb.left	●	●	●	●	✗	0, 100 to 800	0, 100 to 500		
eb.right	●	●	●	●	✗	0, 100 to 800	0, 100 to 500		
eb.blu.top	●	●	●	●	✗		0 to 32 (integer)		
eb.blu.btm	●	●	●	●	✗	0 to 32 (integer)	n/a		
eb.blu.bottom	●	●	●	●	✗	n/a	0 to 32 (integer)		
eb.blu.left	●	●	●	●	✗	0 to 32 (integer)			
eb.blu.right	●	●	●	●	✗	0 to 32 (integer)			
eb.all	✗	✗	●	●	✗	0 to 255 (integer)			
eb.red	●	●	✗	✗	✗	0 to 255 (integer)	0 to 32 (integer)	0 to 255 (integer)	
eb.green	●	●	✗	✗	✗	0 to 255 (integer)	0 to 32 (integer)	0 to 255 (integer)	
eb.blue	●	●	✗	✗	✗	0 to 255 (integer)	0 to 32 (integer)	0 to 255 (integer)	
eb.reset	✗	✗	✗	✗	●	✓	✓	✓	

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Command	Operators allowed					Values accepted / Format of response – per model		
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K
3D								
3d.format	●	●	✗	✗	✗	0 = Off 1 = Auto 2 = Side-By-Side (Half) 3 = Top-And-Bottom 4 = Dual-Pipe 5 = Frame Sequential	n/a	0 = Off 1 = Auto 2 = Side-By-Side (Half) 3 = Top-And-Bottom 4 = Dual-Pipe 5 = Frame Sequential
3d.dlplink	●	●	✗	✗	✗	n/a		0 = Off 1 = On
3d.dominance	●	●	✗	✗	✗	0 = Normal 1 = Reverse	n/a	0 = Normal 1 = Reverse
3d.darktime	●	●	✗	✗	✗	0 = 0.65 ms 1 = 1.3 ms 2 = 1.95 ms 3 = 2.5 ms	n/a	0 = 0.65 ms 1 = 1.3 ms 2 = 1.95 ms
3d.syncoffset	●	●	✗	✗	✗	0 to 60 (integer)	n/a	0 to 200 (integer)
3d.syncref	✗	●	✗	✗	✗	0 = External 1 = Internal	n/a	0 = External 1 = Internal
Laser								
laser.mode	●	●	✗	✗	✗	0 = Eco 1 = Normal 2 = Custom		
laser.power	●	●	✗	✗	✗	30-100 (30%-100% power level; only available when laser.mode=2)	20-100 (20%-100% power level; only available when laser.mode=2)	
laser.hours	✗	●	✗	✗	✗	integer		

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Notes
 laser.power is only effective if laser.mode is set to custom.

Command	Operators allowed		Values accepted / Format of response – per model						Notes	
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K		
Setup										
altitude	●	●	✗	✗	✗	1 = On 2 = Auto	1 = Auto 2 = On	0 = On 1 = Auto 2 = Quiet		
cooling.condition	●	●	✗	✗	✗	n/a		0 = Table 1 = Ceiling 2 = Freetilt 3 = Auto		
orientation	●	●	✗	✗	✗	0 = Desktop Front 1 = Ceiling Front 2 = Desktop Rear 3 = Ceiling Rear		0 = Desktop Front 1 = Ceiling Front 2 = Desktop Rear 3 = Ceiling Rear 4 = Auto-front		
screen.setting	●	●	✗	✗	✗	0 = 16:10 1 = 16:9 2 = 4:3				
auto.poweroff	●	●	✗	✗	✗	0 = Off 1 = On				
auto.poweron	●	●	✗	✗	✗	0 = Off 1 = On				

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Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
schedule.power	●	●	✗	✗	✗	0 = Off 1 = On			
schedule1.on.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule1.off.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule1.on.time	●	●	✗	✗	✗	HH:MM			
schedule1.off.time	●	●	✗	✗	✗	HH:MM			
schedule2.on.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule2.off.day	●	●	✗	✗	✗	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon , Bit0= Sun)			
schedule2.on.time	●	●	✗	✗	✗	HH:MM			
schedule2.off.time	●	●	✗	✗	✗	HH:MM			
date	●	●	✗	✗	✗	yyyy/MM/dd	DD:MM:YYYY	yyyy/MM/dd	
time.zone	●	●	✗	✗	✗	-11 to +12 (integer)			
time.adjust	●	●	✗	✗	✗	HH:MM			
startup.logo	●	●	✗	✗	✗	0 = Off 1 = On			
standby.mode	●	●	✗	✗	✗	n/a	0 = Saving 1 = Eco 2 = Normal		
blank.screen	●	●	✗	✗	✗		0 = Black 1 = Blue 2 = White		

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Command	Operators allowed					Values accepted / Format of response – per model			Notes	
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K		
	●	●	✗	✗	✗	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off				
trig.1	●	●	✗	✗	✗	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off				
trig.2	●	●	✗	✗	✗	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off				
auto.source	●	●	✗	✗	✗	0 = Off 1 = On				

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
ir.enable	●	●	✗	✗	✗	n/a	0 = Off (Disable) 1 = On (Enable)		
ir.code	●	●	✗	✗	✗	00 to 99			
ir.code.rst	✗	✗	✗	✗	●	✓	✓	✓	
osd.lang	●	●	✗	✗	✗	n/a	0 = English 1 = French 2 = Spanish 3 = German 4 = Spanish 5 = Simplified Chinese 6 = Japanese 7 = Korean	0 = English 1 = French 2 = German 3 = Spanish 4 = Simplified Chinese	
osd.menupos	●	●	✗	✗	✗	0 = Top Left 1 = Top Right 2 = Bottom Left 3 = Bottom Right 4 = Center			
osd.trans	●	●	✗	✗	✗	0 = 0% 1 = 25% 2 = 50% 3 = 75%			
osd.timer	●	●	✗	✗	✗	0 = Always On 1 = 10 Seconds 2 = 30 Seconds 3 = 60 Seconds			
osd.msgbox	●	●	✗	✗	✗	0 = Off 1 = On			

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes	
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D		HL Laser 4K		
recall.mem	●	●	✗	✗	✗	0 = Preset A 1 = Preset B 2 = Preset C 3 = Preset D 4 = Default				
save.mem	●	●	✗	✗	✗	0 = Preset A 1 = Preset B 2 = Preset C 3 = Preset D				

Network									
network.mode	●	●	✗	✗	✗	0 = Projector Control 1 = Service	n/a	0 = Projector Control 1 = Service	
lan.power	●	●	✗	✗	✗	0 = Off 1 = On	n/a		
lan.dhcp	●	●	✗	✗	✗	0 = Off 1 = On			
lan.ip	●	●	✗	✗	✗	A valid IP address in the following format: xxx.xxx.xxx.xxx			
lan.subnet	●	●	✗	✗	✗	A valid subnet address in the following format: xxx.xxx.xxx.xxx			
lan.gateway	●	●	✗	✗	✗	A valid gateway address in the following format: xxx.xxx.xxx.xxx			
lan.dns	●	●	✗	✗	✗	A valid DNS address in the following format: xxx.xxx.xxx.xxx			
lan.mac	●	●	✗	✗	✗	string			
lan.amx	●	●	✗	✗	✗	0 = Off 1 = On			

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
PIP									
pip.mode	●	●	✗	✗	✗	0 = Off 1 = On			
pip.input	●	●	✗	✗	✗	0 = HDMI 1 1 = HDMI 2 2 = RGB (VGA) 3 = COMP 4 = DisplayPort 5 = HDBaseT 6 = 3G-SDI	0 = DisplayPort 1 = HDMI 1 2 = HDMI 2 3 = HDBaseT 4 = 3G-SDI	0 = HDMI 1 1 = HDMI 2 2 = DisplayPort 1 3 = DisplayPort 2 4 = HDBaseT 5 = 3G-SDI	
pip.position	●	●	✗	✗	✗	0 = TopLeft 1 = TopRight 2 = BottomLeft 3 = BottomRight 4 = PBP			
Information									
model.name	✗	●	✗	✗	✗	string			
serial	✗	●	✗	✗	✗	string			
sw.version	✗	●	✗	✗	✗	string			
sw1.version	✗	●	✗	✗	✗	n/a	string	n/a	
sw2.version	✗	●	✗	✗	✗	n/a	string	n/a	
sw3.version	✗	●	✗	✗	✗	n/a	string	n/a	
act.source	✗	●	✗	✗	✗	string			
signal	✗	●	✗	✗	✗	string			

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
h.refresh	X	●	X	X	X		number			
v.refresh	X	●	X	X	X		number			
pixel.clock	X	●	X	X	X		number			
laser.hours	X	●	X	X	X		integer			
atmos.alti	X	●	X	X	X		number			
atmos.pressure	X	●	X	X	X		number			
ac.voltage	X	●	X	X	X		0 = 90~150 1 = 160~264			
g.ceiling	X	●	X	X	X		n/a	0 = table 1 = ceiling		
g.portrait	X	●	X	X	X		n/a	number		
g.tilt	X	●	X	X	X		n/a	number		
altitude.info	X	●	X	X	X		n/a	0 = Low 1 = High		
laser.power.info	X	●	X	X	X		n/a	number		
laser.temp							n/a	number	n/a	
ti	X	●	X	X	X		number			
tc	X	●	X	X	X		number			
tb1	X	●	X	X	X		n/a	number		
tb2	X	●	X	X	X		n/a	number		

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model			Notes
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
fan1_3	X	●	X	X	X	n/a			xxxx / xxxx / xxxx (speed of FAN 1~3)	
fan4_6	X	●	X	X	X	n/a			xxxx / xxxx / xxxx (speed of FAN 4~6)	
fan7_9	X	●	X	X	X	n/a			xxxx / xxxx / xxxx (speed of FAN 7~9)	
fan10_12	X	●	X	X	X	n/a			xxxx / xxxx / xxxx (speed of FAN 10~12)	
fan13_15	X	●	X	X	X	n/a			xxxx / xxxx / xxxx (speed of FAN 13~15)	
fan16_18	X	●	X	X	X	n/a			xxxx / xxxx / xxxx (speed of FAN 16)	
fans	X	●	X	X	X	All fan & environment status			n/a	
water.pump	X	●	X	X	X	number	n/a		number	
water.pump1	X	●	X	X	X	n/a	number		n/a	
water.pump2	X	●	X	X	X	n/a	number		number	
water.pump3	X	●	X	X	X	n/a	number		n/a	
factory.reset	X	X	X	X	●	✓	✓		✓	

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Command	Operators allowed		Values accepted / Format of response – per model						Notes
	Set =	Get ?	Inc +	Dec -	Exe	HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K	
Miscellaneous									
power	●	●	✗	✗	✗	0 = Off 1 = On			
shutter	●	●	✗	✗	✗	0 = Open 1 = Close	n/a		
pic.mute	●	●	✗	✗	✗	n/a	0 = Open 1 = Close		
total.hours	✗	●	✗	✗	✗	number			
status	✗	●	✗	✗	✗	0 = Standby 1 = Warm Up 2 = Imaging 3 = Cooling 4 = Error			
errcode	✗	●	✗	✗	✗	string			
sys.info	✗	●	✗	✗	✗	n/a	string		

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Command	Operators allowed						Values accepted / Format of response – per model			Notes	
	Set =	Get ?	Inc +	Dec -	Exe		HL Laser II 3D	HL Laser 4K	M-Vision Laser 18K		
dlp.pattern	●	X	X	X	X	n/a	0 = Off 1 = RGB Ramps 2 = Color Bar 3 = Step Bars 4 = Check Board 5 = Grid6 = H Lines 7 = V Lines 8 = D Lines 9 = Ramp H 10 = Ramp V 11 = White 12 = Red 13 = Green 14 = Blue 15 = Black 16 = Cyan 17 = Magenta 18 = Yellow	n/a			
pri.reset	X	X	X	X	●	n/a	✓	n/a			
sp.power	X	●	X	X	X		0 = Off 1 = On				
sp.index.v sp.index.h	●	●	X	X	X	n/a	0, 0 to 4096	n/a			
warp.key	X	●	X	X	X	n/a	0 = licence fail, timeout expired 1 = licence pass, timeout expired 2 = licence fail, timeout not expired 3 = licence pass, timeout not expired	n/a			

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E-Vision 6900 Series Mercury Quad Series

High Brightness Digital Video Projector

► PROTOCOL GUIDE



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Introduction

The projector can be controlled by using an external control system or a PC via an RS232 or LAN interface, using a terminal-emulation program.

Network setup

1. Connect the projector to a LAN network.
2. Open the **Setup > Network** menu and edit network settings. The default IP address is **192.168.0.100** and the TCP port number is **7000**.

Serial Port setup

- Baud rate 9,600 bps
- Data length 8 bits
- Stop bits one
- Parity none
- Flow control none

Notes

 For details on connecting the projector to an RS232 or LAN network, or changing network settings, see the user manual.

 Only one control path at a time should be used for protocol control. Attempts to send commands to both serial and network ports at the same time may result in unpredictable behavior.

Protocol commands

Commands are used to simulate menu operations and determine the settings of the projector, and use the following format:

- All commands consist of ASCII text strings starting with an asterisk* and ending with an ASCII Carriage Return character ↵ (code 13):
*command operator <value>↵
- The <command> string determines which setting the command will affect.
- Spaces are required before the operator and before the value.
- The <operator> string can take one of the following formats:

Command type	<operator>	Description
Set	= <value>	Makes the setting take the <value>.
Get	?	Asks what the current value is. The value is returned as an ASCII text string.
Execute		Performs an action. No operator is entered for this type of command.

Notes

 To set the default value of a command, simply enter the command name and ↵, without an operator. For example *orientation↵ will set the orientation to 0 (Desktop Front).

 You must wait for the complete response to a command before sending another command.

Examples

- *orientation = 3↵ sets the orientation to Rear Ceiling (for a ceiling mounted projector positioned behind the screen)
 *aspect.ratio ?↵ asks what the current aspect ratio is
 *zoom.in↵ commands the projector to zoom in
 *orientation=3↵ is an invalid instruction because of the missing spaces before the operator and the value

Responses

If the command has been successful, the projector response begins with ACK or ack ("acknowledged"). For example, if the command is *aspect.ratio = 1↵, the projector will return ACK aspect.ratio = 1↵ or ack aspect.ratio = 1↵, depending on the model. In either case the projector will then change the aspect ratio accordingly.

If the command has not been acknowledged, due to a syntax error or another problem, the projector response will be NAK or nack, followed by a brief description of the problem.

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Input								
input	●	●	✗	✗	✗	0 = HDMI I 1 = HDMI II 2 = DVI-D 3 = VGA 4 = Component 5 = HDBaseT	0 = HDMI 1 1 = HDMI 2 2 = DisplayPort 3 = HDBaseT 4 = 3G-SDI	
Test Pattern								
test.pattern	●	●	✗	✗	✗	0 = Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Checkboard 7 = CrossHatch 8 = V Burst 9 = H Burst 10 = Color Bar 11 = Hramp	0 = Off 1 = White 2 = Black 3 = Red 4 = Green 5 = Blue 6 = Checkerboard 7 = Crosshatch 8 = V Burst 9 = H Burst 10 = Color Bar 11 = Plunge	

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Command	Operators allowed						Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Lens								
zoom.in	X	X	X	X	●	✓	✓	
zoom.out	X	X	X	X	●	✓	✓	
focus.near	X	X	X	X	●	✓	✓	
focus.far	X	X	X	X	●	✓	✓	
lens.up	X	X	X	X	●	✓	✓	
lens.down	X	X	X	X	●	✓	✓	
lens.left	X	X	X	X	●	✓	✓	
lens.right	X	X	X	X	●	✓	✓	
lens.center	X	X	X	X	●	✓	✓	
lens.load	●	X	X	X	X	0 to 9 (integer)	1 to 10 (integer)	
lens.save	●	X	X	X	X	0 to 9 (integer)	1 to 10 (integer)	
lens.clear	●	X	X	X	X	0 to 9 (integer)	1 to 10 (integer)	
lens.type	●	●	X	X	X	0 = non-UST Lens 1 = UST Lens	n/a	
lens.lock	●	●	X	X	X	0 = Off 1 = On		

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Notes

 Lens commands only work if the projector is switched on.

 To use lens commands, make sure the lens is unlocked. If lens.lock is set to 1, most other lens commands are disabled.

Exceptions are:

- lens.type - for all models
- lens.save and lens.clear - for Mercury Quad.

 When used with a get operator, the lens.save command returns a string of zeroes and ones where each zero is an empty memory slot and each one is an occupied slot.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
Image							
pic.mode	●	●	✗	✗	✗	0 = High Bright 1 = Presentation 2 = Video	n/a
dblack	●	●	✗	✗	✗	0 = Off 1 = On	n/a
gamma	●	●	✗	✗	✗	0 = 1.0 1 = 1.8 2 = 2.0 3 = 2.2 4 = 2.35 5 = 2.5 6 = S-curve	0 = 1.0 1 = 1.8 2 = 2.0 3 = 2.2 4 = 2.35 5 = 2.5
brightness	●	●	●	●	✗	n/a	0 to 200 (integer)
	●	●	✗	✗	✗	0 to 200 (integer)	n/a
contrast	●	●	●	●	✗	n/a	0 to 200 (integer)
	●	●	✗	✗	✗	0 to 200 (integer)	n/a
saturation	●	●	●	●	✗	n/a	0 to 200 (integer)
	●	●	✗	✗	✗	0 to 200 (integer)	n/a
hue	●	●	●	●	✗	n/a	0 to 200 (integer)
	●	●	✗	✗	✗	0 to 200 (integer)	n/a
sharpness	●	●	●	●	✗	n/a	0 to 15 (integer)
	●	●	✗	✗	✗	0 to 31 (integer)	n/a

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Notes
 The values you set of pic.mode, gamma, brightness, contrast, saturation and hue will only apply to the current image source.
 dblack is not available in 3D.
 E-Vision 6900 will only accept saturation and hue values if the input is YUV.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
nr	●	●	✗	✗	✗	0 to 15 (integer)	n/a
nr.temporal	●	●	●	●	✗	n/a	0 to 3 (integer)
nr.block	●	●	●	●	✗	n/a	0 to 3 (integer)
nr.mosquito	●	●	●	●	✗	n/a	0 to 3 (integer)
nr.hori	●	●	●	●	✗	n/a	0 to 3 (integer)
nr.vert	●	●	●	●	✗	n/a	0 to 3 (integer)
nr.reset	●	●	✗	✗	✗	n/a	0 to 3 (integer)
h.position	●	●	●	●	✗	0 to 200 (integer)	
v.position	●	●	●	●	✗	0 to 200 (integer)	
vga.phase	●	●	●	●	✗	0 to 31 (integer)	
tracking	●	●	●	●	✗	0 to 200 (integer)	
sync.level	●	●	●	●	✗	n/a	0 to 200 (integer)
freeze	●	●	✗	✗	✗	0 = Off 1 = On	
resync	✗	✗	✗	✗	●	n/a	✓
vga.auto	✗	✗	✗	✗	●	✓	n/a

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Notes
 The commands on this page will only apply to the current image source.
 The vga.phase command is identical to the Phase setting in the Image > Position and Phase menu.

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Color								
color.space	●	●	✗	✗	✗	0 = Auto 1 = YPbPr 2 = YCbCr 3 = RGB-PC 4 = RGB-Video		
color.temp	●	●	✗	✗	✗	0 = Native 1 = 5400K 2 = 6500K 3 = 7500K 4 = 9300K	0 = 3200K 1 = 5400K 2 = 6500K 3 = 7500K 4 = 9300K 5 = Native	
color.mode	●	●	✗	✗	✗	n/a	0 = ColorMax 1 = Manual Color Matching 2 = Color Temperature 3 = Gains and Lifts	
color.max	●	●	✗	✗	✗	n/a	0 = REC709 1 = EBU 2 = SMPTE 3 = Native 4 = User 1 5 = User 2	

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
red.lift	●	●	●	●	✗	0 to 200 (integer)	
green.lift	●	●	●	●	✗	0 to 200 (integer)	
blue.lift	●	●	●	●	✗	0 to 200 (integer)	
red.gain	●	●	●	●	✗	0 to 200 (integer)	
green.gain	●	●	●	●	✗	0 to 200 (integer)	
blue.gain	●	●	●	●	✗	0 to 200 (integer)	
gainlift.reset	✗	✗	✗	✗	●	n/a	✓
auto.test.ptrn	●	●	✗	✗	✗	n/a	0 = Off 1 = On
user.std.rx	●	●	✗	✗	✗	n/a	550 to 750 (integer)
user.std.ry	●	●	✗	✗	✗	n/a	250 to 450 (integer)
user.std.gx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user.std gy	●	●	✗	✗	✗	n/a	400 to 750 (integer)
user.std.bx	●	●	✗	✗	✗	n/a	50 to 250 (integer)
user.std.by	●	●	✗	✗	✗	n/a	0 to 120 (integer)
user.std.wx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user.std.wy	●	●	✗	✗	✗	n/a	250 to 450 (integer)
user.std.reset	✗	✗	✗	✗	●	n/a	✓

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Notes



The user.std commands are identical to the settings in the **Setup > ColorMax > Measured Data** menu. Protocol values are multiples of 1000.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
user.target.rx	●	●	✗	✗	✗	n/a	550 to 750 (integer)
user.target.ry	●	●	✗	✗	✗	n/a	250 to 450 (integer)
user.target.gx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user.target gy	●	●	✗	✗	✗	n/a	400 to 750 (integer)
user.target.bx	●	●	✗	✗	✗	n/a	50 to 250 (integer)
user.target.by	●	●	✗	✗	✗	n/a	0 to 120 (integer)
user.target.wx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user.target.wy	●	●	✗	✗	✗	n/a	250 to 450 (integer)
user.target.cx	●	●	✗	✗	✗	n/a	125 to 325 (integer)
user.target.cy	●	●	✗	✗	✗	n/a	225 to 425 (integer)
user.target.mx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user.target.my	●	●	✗	✗	✗	n/a	50 to 250 (integer)
user.target.yx	●	●	✗	✗	✗	n/a	300 to 500 (integer)
user.target.yy	●	●	✗	✗	✗	n/a	400 to 600 (integer)
user.target.reset	✗	✗	✗	✗	●	n/a	✓

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Notes
 The user.target commands are identical to the settings in the Setup > ColorMax > Target Data — User 1 menu. Protocol values are multiples of 1000.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
user2.target.rx	●	●	✗	✗	✗	n/a	550 to 750 (integer)
user2.target.ry	●	●	✗	✗	✗	n/a	250 to 450 (integer)
user2.target.gx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user2.target gy	●	●	✗	✗	✗	n/a	400 to 750 (integer)
user2.target.bx	●	●	✗	✗	✗	n/a	50 to 250 (integer)
user2.target.by	●	●	✗	✗	✗	n/a	0 to 120 (integer)
user2.target.wx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user2.target.wy	●	●	✗	✗	✗	n/a	250 to 450 (integer)
user2.target.cx	●	●	✗	✗	✗	n/a	125 to 325 (integer)
user2.target.cy	●	●	✗	✗	✗	n/a	225 to 425 (integer)
user2.target.mx	●	●	✗	✗	✗	n/a	200 to 400 (integer)
user2.target.my	●	●	✗	✗	✗	n/a	50 to 250 (integer)
user2.target.yx	●	●	✗	✗	✗	n/a	300 to 500 (integer)
user2.target.yy	●	●	✗	✗	✗	n/a	400 to 600 (integer)
user2.target.reset	✗	✗	✗	✗	●	n/a	✓

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Notes
 The user2.target commands are identical to the settings in the Setup > ColorMax > Target Data — User 2 menu. Protocol values are multiples of 1000.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
hsg.hue.r	●	●	●	●	×	0 to 200 (integer)	
hsg.hue.g	●	●	●	●	×	0 to 200 (integer)	
hsg.hue.b	●	●	●	●	×	0 to 200 (integer)	
hsg.hue.c	●	●	●	●	×	0 to 200 (integer)	
hsg.hue.m	●	●	●	●	×	0 to 200 (integer)	
hsg.hue.y	●	●	●	●	×	0 to 200 (integer)	
hsg.sat.r	●	●	●	●	×	0 to 200 (integer)	
hsg.sat.g	●	●	●	●	×	0 to 200 (integer)	
hsg.sat.b	●	●	●	●	×	0 to 200 (integer)	
hsg.sat.c	●	●	●	●	×	0 to 200 (integer)	
hsg.sat.m	●	●	●	●	×	0 to 200 (integer)	
hsg.sat.y	●	●	●	●	×	0 to 200 (integer)	

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Notes
 The hsg commands are identical to the settings in the Color > Manual Color Matching menu.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
hsg.gain.r	●	●	●	●	✗	0 to 200 (integer)	
hsg.gain.g	●	●	●	●	✗	0 to 200 (integer)	
hsg.gain.b	●	●	●	●	✗	0 to 200 (integer)	
hsg.gain.c	●	●	●	●	✗	0 to 200 (integer)	
hsg.gain.m	●	●	●	●	✗	0 to 200 (integer)	
hsg.gain.y	●	●	●	●	✗	0 to 200 (integer)	
hsg.white.r	●	●	●	●	✗	0 to 200 (integer)	
hsg.white.g	●	●	●	●	✗	0 to 200 (integer)	
hsg.white.b	●	●	●	●	✗	0 to 200 (integer)	
hsg.reset	✗	✗	✗	✗	●	n/a	✓

Continues on next page...

Notes
 The hsg commands are identical to the settings in the Color > Manual Color Matching menu.

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
Geometry							
aspect.ratio	●	●	✗	✗	✗	0 = 5:4 1 = 4:3 2 = 16:10 3 = 16:9 4 = 1.88 5 = 2.35 6 = Theaterscope 7 = Source 8 = Unscaled	
digi.zoom	●	●	✗	✗	✗	n/a	0 to 100 (integer)
digi.pan	●	●	✗	✗	✗	n/a	-320 to +320 (integer)
digi.pan.bound	✗	●	✗	✗	✗	n/a	-320 to +320 (integer)
digi.scan	●	●	✗	✗	✗	n/a	-200 to +200 (integer)
digi.scan.bound	✗	●	✗	✗	✗	n/a	-200 to +200 (integer)
digi.zoom.rst	✗	✗	✗	✗	●	n/a	✓
overscan	●	●	✗	✗	✗	0 = Off 1 = Crop 2 = Zoom	0 = Off 1 = Crop 2 = Zoom
h.keystone	●	●	●	●	✗	-30 to +30 (integer)	-600 to +600 (integer)
v.keystone	●	●	●	●	✗	-30 to +30 (integer)	-400 to +400 (integer)
rotation	●	●	●	●	✗	n/a	-100 to +100 (integer)
h.pin.barrel	●	●	●	●	✗	n/a	-150 to +300 (integer)
v.pin.barrel	●	●	●	●	✗	n/a	-150 to +300 (integer)

Continues on next page...

Notes

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
4corner.ulx	●	●	●	●	✗	n/a	-192 to +192 (integer)	
4corner.uly	●	●	●	●	✗	n/a	-120 to +120 (integer)	
4corner.urx	●	●	●	●	✗	n/a	-192 to +192 (integer)	
4corner.ury	●	●	●	●	✗	n/a	-120 to +120 (integer)	
4corner.llx	●	●	●	●	✗	n/a	-192 to +192 (integer)	
4corner.lly	●	●	●	●	✗	n/a	-120 to +120 (integer)	
4corner.lrx	●	●	●	●	✗	n/a	-192 to +192 (integer)	
4corner.lry	●	●	●	●	✗	n/a	-120 to +120 (integer)	
arc.top	●	●	●	●	✗	n/a	-150 to +150 (integer)	
arc.bottom	●	●	●	●	✗	n/a	-150 to +150 (integer)	
arc.left	●	●	●	●	✗	n/a	-150 to +150 (integer)	
arc.right	●	●	●	●	✗	n/a	-150 to +150 (integer)	
blanking.top	●	●	●	●	✗	n/a	0 to 360 (integer)	
blanking.bottom	●	●	●	●	✗	n/a	0 to 360 (integer)	
blanking.left	●	●	●	●	✗	n/a	0 to 534 (integer)	
blanking.right	●	●	●	●	✗	n/a	0 to 534 (integer)	
blanking.reset	✗	✗	✗	✗	●	n/a	✓	

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision 6900	Mercury Quad	
warp.reset	X	X	X	X	●	n/a		✓	
active.warp	●	●	X	X	X	n/a	0 = none (no warp function is set) 1 = Keystone 2 = Four Coner 3 = Rotation 4 = Pin/Barrel 5 = Arc		
cust.wp.write	●	X	X	X	X	n/a	1 = User 1 file 2 = User 2 file		
cust.wp.clear	●	X	X	X	X	n/a	1 = User 1 file 2 = User 2 file		
cust.wp.send	●	●	X	X	X	n/a	0 = custom warp transfer mode off 1 = custom warp transfer User 1 file 2 = custom warp transfer User 2 file		
cust.wp.ck.sum	X	●	X	X	X	n/a	Returns the unsigned 32 bits checksum by summing all bytes in the current sent warp file when cust.wp.send is not zero		
warp.cust	●	●	X	X	X	n/a	0 = Off 1 = User 1 2 = User 2		

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Edge Blend								
eb.stat	●	●	✗	✗	✗	n/a	0 = Off 1 = On	
eb.adl	●	●	✗	✗	✗	n/a	0 = Off 1 = On	
eb.top	●	●	●	●	✗	n/a	0, 100 to 500	
eb.bottom	●	●	●	●	✗	n/a	0, 100 to 500	
eb.left	●	●	●	●	✗	n/a	0, 100 to 800	
eb.right	●	●	●	●	✗	n/a	0, 100 to 800	
eb.blu.top	●	●	●	●	✗	n/a	0 to 32 (integer)	
eb.blu.btm	●	●	●	●	✗	n/a	0 to 32 (integer)	
eb.blu.left	●	●	●	●	✗	n/a	0 to 32 (integer)	
eb.blu.right	●	●	●	●	✗	n/a	0 to 32 (integer)	
eb.all	✗	✗	●	●	✗	n/a	0 to 255 (integer)	
eb.red	●	●	✗	✗	✗	n/a	0 to 255 (integer)	
eb.green	●	●	✗	✗	✗	n/a	0 to 255 (integer)	
eb.blue	●	●	✗	✗	✗	n/a	0 to 255 (integer)	
eb.reset	✗	✗	✗	✗	●	n/a	✓	

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
3D							
3d.format	●	●	✗	✗	✗	0 = Off 1 = Auto 2 = Side-By-Side (Half) 3 = Top-And-Bottom 4 = Frame Sequential	0 = Off 1 = Auto 2 = Side-By-Side (Half) 3 = Top-And-Bottom 4 = Dual-Pipe 5 = Frame Sequential
3d.dlplink	●	●	✗	✗	✗	0 = Off 1 = On	n/a
3d.dominance	●	●	✗	✗	✗	0 = Normal 1 = Reverse	
3d.darktime	●	●	✗	✗	✗	n/a	0 = 0.65 ms 1 = 1.3 ms 2 = 1.95 ms 3 = 2.5 ms
3d.syncoffset	●	●	✗	✗	✗	0 to 200 (integer)	0 to 60 (integer)
3d.syncref	●	●	✗	✗	✗	0 = Internal 1 = External	n/a
	✗	●	✗	✗	✗	n/a	0 = Internal 1 = External

Continues on next page...

Notes

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Lamp								
lamp.mode	●	●	✗	✗	✗	0 = Dual 1 = Single 2 = Lamp 1 3 = Lamp 2	0 = Eco mode 1 = Normal mode 2 = dimming mode	
lamps	●	●	✗	✗	✗	n/a	0 = Dual Lamps 1 = Triple Lamps 2 = Quad Lamps	
power.mode	●	●	✗	✗	✗	0 = Normal 1 = Eco 2 = Custom Power Level	n/a	
lamp.power	●	●	✗	✗	✗	0-26 (80%~100%)	n/a	
lamp.pow	●	●	✗	✗	✗	n/a	77-100 (77%-100%)	
lamp1.hours	✗	●	✗	✗	✗	number		
lamp2.hours								

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Setup								
altitude	●	●	✗	✗	✗	1 = Off 2 = On	1 = On 2 = Auto	
cooling.condition	●	●	✗	✗	✗	0 = Table 1 = Ceiling 2 = Upward 3 = Downward	n/a	
orientation	●	●	✗	✗	✗	0 = Desktop Front 1 = Ceiling Front 2 = Desktop Rear 3 = Ceiling Rear	0 = Desktop Front 1 = Ceiling Front 2 = Desktop Rear 3 = Ceiling Rear 4 = Vertical Up 5 = Vertical Down	
screen.setting	●	●	✗	✗	✗	n/a	0 = 16:10 1 = 16:9 2 = 4:3	
screen.format	●	●	✗	✗	✗	0 = 16:10 1 = 16:9 2 = 4:3	n/a	
screen.shift	●	●	✗	✗	✗	If screen.format = 16:10 => 0 = 16:9 => -60 ~ 60 = 4:3 => -160 ~160	n/a	
auto.poweroff	●	●	✗	✗	✗	0 = Off 1 = On		
auto.poweron	●	●	✗	✗	✗	0 = Off 1 = On		

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe		E-Vision 6900	Mercury Quad
schedule.power	●	●	✗	✗	✗	n/a	0 = Off 1 = On	
schedule1.on.day	●	●	✗	✗	✗	n/a	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon, Bit0= Sun)	
schedule1.off.day	●	●	✗	✗	✗	n/a	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon, Bit0= Sun)	
schedule1.on.time	●	●	✗	✗	✗	n/a	HH:MM	
schedule1.off.time	●	●	✗	✗	✗	n/a	HH:MM	
schedule2.on.day	●	●	✗	✗	✗	n/a	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon, Bit0= Sun)	
schedule2.off.day	●	●	✗	✗	✗	n/a	= 76543210 (Bit 6 = Sat, Bit5 = Fri, Bit4 = Thu, Bit3 = Wed, Bit2 = Tue, Bit1 = Mon, Bit0= Sun)	
schedule2.on.time	●	●	✗	✗	✗	n/a	HH:MM	
schedule2.off.time	●	●	✗	✗	✗	n/a	HH:MM	
date	●	●	✗	✗	✗	n/a	yyyy/MM/dd	
time.zone	●	●	✗	✗	✗	n/a	-11 to +12 (integer)	
time.adjust	●	●	✗	✗	✗	n/a	HH:MM	
startup.logo	●	●	✗	✗	✗	0 = Off 1 = On		
blank.screen	●	●	✗	✗	✗	0 = Logo 1 = Black 2 = Blue 3 = White	0 = Logo 1 = Black 2 = Blue 3 = White	

Continues on next page...

Notes

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
trig.1	●	●	✗	✗	✗	0 = Off 1 = On	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off	
trig.2	●	●	✗	✗	✗	n/a	0 = Off 1 = Screen 2 = 5:4 3 = 4:3 4 = 16:10 5 = 16:9 6 = 1.88 7 = 2.35 8 = Theaterscope 9 = Source 10 = Unscalled 11 = RS232 12 = RS232 on 13 = RS232 off	
auto.source	●	●	✗	✗	✗	n/a	0 = Off 1 = On	
auto.src	●	●	✗	✗	✗	0 = Off 1 = On	n/a	

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
ir.enable	●	●	✗	✗	✗	n/a	0 = Off (Disable) 1 = On (Enable)
ir.code	●	●	✗	✗	✗	n/a	00 to 99
ir.code.rst	✗	✗	✗	✗	●	n/a	✓
control.id	●	●	✗	✗	✗	00~99 (0=Disable, 1~99=Enable)	n/a
osd.lang	●	●	✗	✗	✗	0 = English 1 = French 2 = Spanish 3 = German 4 = Portuguese 5 = CHS 6 = CHT 7 = Janpanese 8 = Korean	n/a
osd.menupos	●	●	✗	✗	✗	0 = Center 1 = Top Left 2 = Top Right 3 = Bottom Left 4 = Bottom Right	0 = Top Left 1 = Top Right 2 = Bottom Left 3 = Bottom Right 4 = Center
osd.trans	●	●	✗	✗	✗	n/a	0 = 0% 1 = 25% 2 = 50% 3 = 75%
osd.timer	●	●	✗	✗	✗	0 = Always On 1 = 10 Seconds 2 = 30 Seconds 3 = 60 Seconds	
osd.msgbox	●	●	✗	✗	✗	0 = Off 1 = On	

Notes

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
recall.mem	●	●	✗	✗	✗	n/a	0 = Preset A 1 = Preset B 2 = Preset C 3 = Preset D 4 = Default	
save.mem	●	●	✗	✗	✗	n/a	0 = Preset A 1 = Preset B 2 = Preset C 3 = Preset D	

Continues on next page...

Command	Operators allowed					Values accepted / Format of response – per model	
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad
Network							
network.mode	●	●	✗	✗	✗	n/a	0 = Projector Control 1 = Service
lan.power	●	●	✗	✗	✗	0 = On 1 = Off	
lan.dhcp	●	●	✗	✗	✗	0 = On 1 = Off	
lan.ip	●	●	✗	✗	✗	A valid IP address in the following format: xxx.xxx.xxx.xxx	
lan.subnet	●	●	✗	✗	✗	A valid subnet address in the following format: xxx.xxx.xxx.xxx	
lan.gateway	●	●	✗	✗	✗	A valid gateway address in the following format: xxx.xxx.xxx.xxx	
lan.dns	●	●	✗	✗	✗	A valid DNS address in the following format: xxx.xxx.xxx.xxx	
lan.mac	●	●	✗	✗	✗	n/a	string
lan.amx	●	●	✗	✗	✗	n/a	0 = On 1 = Off
PIP							
pip.mode	●	●	✗	✗	✗	n/a	0 = On 1 = Off
pip.input	●	●	✗	✗	✗	n/a	0 = HDMI 1 1 = HDMI 2 2 = RGB (VGA) 3 = COMP 4 = DisplayPort 5 = HDBaseT 6 = 3G-SDI
pip.position	●	●	✗	✗	✗	n/a	0 = TopLeft 1 = TopRight 2 = BottomLeft 3 = BottomRight 4 = PBP

*Continues on next page...***Notes**

Command	Operators allowed					Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad	
Information								
model.name	X	●	X	X	X	string		
serial	X	●	X	X	X	string		
sw.version	X	●	X	X	X	string		
act.source	X	●	X	X	X	string		
signal	X	●	X	X	X	string		
h.refresh	X	●	X	X	X	number		
v.refresh	X	●	X	X	X	number		
pixel.clock	X	●	X	X	X	number		
lamp1.hours	X	●	X	X	X	n/a	integer	
lamp2.hours	X	●	X	X	X	n/a	integer	
lamp3.hours	X	●	X	X	X	n/a	integer	
lamp4.hours	X	●	X	X	X	n/a	integer	
brt.lock.pw	●	X	X	X	X	n/a	XXXX(4 digits = user or supervisor mode password)	
brt.lock.pw.set	●	X	X	X	X	n/a	XXXX(4 digits = new user mode password)	
brt.lock.level	●	●	X	X	X	n/a	0 = Dual Lamps 1 = Triple Lamps 2 = Quad Lamps	
brt.lock.rst	X	X	X	X	●	n/a	✓	

Continues on next page...

Command	Operators allowed						Values accepted / Format of response – per model		Notes
	Set =	Get ?	Inc +	Dec -	Exe	E-Vision 6900	Mercury Quad		
atmos.alti	X	●	X	X	X	n/a	number		
atmos.pressure	X	●	X	X	X	n/a	number		
ac.voltage	X	●	X	X	X	n/a	0 = 90~150 1 = 160~264		
ti	X	●	X	X	X	number			
tc	X	●	X	X	X	number			
fans	X	●	X	X	X	All fan & environment status			
factory.reset	X	X	X	X	●	n/a	✓		
Miscellaneous									
power	●	●	X	X	X	0 = Off 1 = On			
shutter	●	●	X	X	X	n/a	0 = Open 1 = Close		
pic.mute	●	●	X	X	X	0 = Open 1 = Close	n/a		
total.hours	X	●	X	X	X	n/a	integer		
status	X	●	X	X	X	0 = Power Off 1 = Power On	0 = Standby 1 = Warm Up 2 = Imaging 3 = Cooling 4 = Error		
errcode	X	●	X	X	X	n/a	string		



INSIGHT Dual Laser 4K Series

INSIGHT 4K Quad Series

INSIGHT 4K Dual LED Series

High Brightness Digital Video Projector

► PROTOCOL GUIDE



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Introduction

The projector can be controlled by using an external control system or a PC via an RS232 or LAN interface, using a terminal-emulation program.

Network setup

The projector must have an IP address assigned to it before it can be controlled via protocol commands. The IP address can be user assigned or DHCP assigned..

Setting a user assigned IP address

Set a static IP address by using the OSD. Navigate to the **Network** page on the OSD. Make sure that the **DHCP** checkbox is unchecked and set your desired IP address. See the *User Manual* for details.

Setting a DHCP assigned IP address

To enable a DHCP assigned IP address to be set, navigate to the **Network** page on the OSD and make sure that the **DHCP** checkbox is checked. See the *User Manual* for details

Most home and workplace networks have a DHCP server built into the network router. If this is the case, connect the projector and the control PC to the network and log into the router's DHCP client list to find the IP address assigned to the projector. Alternatively, launch the DP Projector Controller software and use it to display the projector's IP address as shown in *Fig. 1*.

Network Port setup

- IP address assigned by DHCP
- Port 7000

Serial Port setup

- Baud rate 38,400 bps
- Data length 8 bits
- Stop bits one
- Parity none
- Flow control none

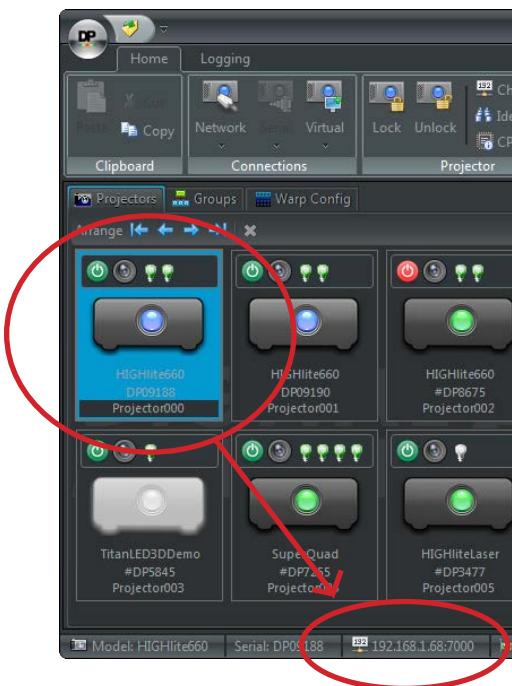


Fig. 1

Notes

Only one control path at a time should be used for protocol control. Attempts to send commands to both serial and network ports at the same time may result in unpredictable behavior.

Protocol commands

Commands are used to simulate menu operations and determine the settings of the projector, and use the following format:

- All commands consist of ASCII text strings starting with an asterisk* and ending with an ASCII Carriage Return character↵ (code 13):
`*command operator <value>↵`
- The **<command>** string determines which setting the command will affect.
- Spaces are required before the operator and before the value.
- The **<operator>** string can take one of the following formats:

Command type	<operator>	Description
Set	= <value>	Makes the setting take the <value>.
Get	?	Asks what the current value is. The value is returned as an ASCII text string.
Increment	+	Adds 1 to the current value.
Increment by x	+x	Adds x to the current value, where x is an integer
Decrement	-	Subtracts 1 from the current value.
Decrement by x	-x	Subtracts x from the current value, where x is an integer
Default	#	Assigns the default value.
Execute		Performs an action. No operator is entered for this type of command.

Notes

 You must wait for the complete response to a command before sending another command.

 You cannot increment or decrement past the maximum / minimum value.

Examples

*orientation = 3 ↴	sets the orientation to Rear Ceiling (for a ceiling mounted projector positioned behind the screen)
*orientation ? ↴	asks what the current orientation is
*brightness + ↴	increases the current brightness value by 1
*brightness +10 ↴	increases the current brightness value by 10
*brightness - ↴	decreases the current brightness value by 1
*brightness -10 ↴	decreases the current brightness value by 10
*brightness # ↴	sets the default brightness value
*zoom.in ↴	commands the projector to zoom in
*orientation=3 ↴	is an invalid instruction because of the missing spaces before the operator and the value

Notes

 You cannot increment or decrement past the maximum / minimum value.

Responses

If the command has been successful, the projector response begins with ack (“acknowledged”). For example, if the command is

*orientation = 1 ↴, the projector will return ack orientation = 1 ↴. The projector will then change the orientation accordingly.

If the command has not been acknowledged, due to a syntax error or another problem, the projector response will be nack, followed by a brief description of the problem.

Power

<command>	<operator>	<values>
power	= ?	on off
standby.mode	= ?	normal super

Inputs

<command>	<operator>	<values>
input	= ?	0 = HDMI A 1 = HDMI B 2 = DisplayPort A 3 = DisplayPort B 6 = DisplayPort A+B Dual Pipe (East/West) 7 = DisplayPort A+B Dual Pipe (Left/Right)
input.next	(execute)	
input.prev	(execute)	
input.max	?	

Test Patterns

<command>	<operator>	<value>
formatter.pattern	= ?	13 = native white 14 = native black 15 = native green 16 = native red 17 = native blue 21 = off

Notes

 In normal standby the projector will consume more power in standby mode but will start up more quickly. In super standby the projector will consume less power in standby mode but will start up more slowly.

 input values 6 and 7 are only available on video processor software version 29.00 and above.

 input.next selects the next input in the list as follows:
...HDMI A, HDMI B, DisplayPort A, DisplayPort B...

Alternatively, enter input.prev to select the previous input from the list.

 input.max returns the number of the highest available input.

Lens

<command>	<operator>	<value>
zoom.in	(execute)	
zoom.out	(execute)	
focus.near	(execute)	
focus.far	(execute)	
lens.center	(execute)	
lens.up	=	0 - 3 (integer, movement speed: 0 = slowest, 3 = fastest)
lens.down	=	0 - 3 (integer, movement speed: 0 = slowest, 3 = fastest)
lens.left	=	0 - 3 (integer, movement speed: 0 = slowest, 3 = fastest)
lens.right	=	0 - 3 (integer, movement speed: 0 = slowest, 3 = fastest)
lens.stop	(execute)	
nudge.up	=	0 - 3 (integer, nudge time: 0 = shortest, 3 = longest)
nudge.down	=	0 - 3 (integer, nudge time: 0 = shortest, 3 = longest)
nudge.left	=	0 - 3 (integer, nudge time: 0 = shortest, 3 = longest)
nudge.right	=	0 - 3 (integer, nudge time: 0 = shortest, 3 = longest)
calibrate.zoom	(execute)	
calibrate.focus	(execute)	
lensmemory.save	=	0 - 9 (integer)
lensmemory.recall	=	0 - 9 (integer)

Image

<command>	<operator>	<value>
brightness	= ? + - #	-50 to 50 (integer)
contrast	= ? + - #	-50 to 50 (integer)
gamma	= ? #	10 to 30 (integer)
freeze	= ?	on, off

Notes

 When lens.up, lens.down, lens.left or lens.right is sent, the movement will continue until either a lens.stop command is sent or the limit is reached. Use a nudge command to produce a brief movement of the lens in the specified direction.

 The gamma values correspond to gamma values of 1.0 to 3.0.

The get operator always returns a parametric value.

 When freeze is switched on, the image freezes and the projector will keep displaying the frozen frame until *freeze = off ↩ is sent. The frozen image will persist even if you disconnect the source.

Color

<command>	<operator>	<values>
mcgd.data	= ?	green-x, green-y, red-x, red-y, blue-x, blue-y, white-x, white-y
mcgd.factory	(execute)	
tcgd.data	= ?	green-x, green-y, red-x, red-y, blue-x, blue-y, white-x, white-y
gamut	=	0 = Peak 1 = Rec. 709 2 = Rec. 601 3 = 3200K 4 = 5400K 5 = 6500K 6 = 8000K 7 = 9000K
red.lift	= ? + - #	-50 to +50 (integer)
green.lift	= ? + - #	-50 to +50 (integer)
blue.lift	= ? + - #	-50 to +50 (integer)
red.gain	= ? + - #	-50 to +50 (integer)
green.gain	= ? + - #	-50 to +50 (integer)
blue.gain	= ? + - #	-50 to +50 (integer)
csc.matrix	= ?	c1, c2, c3, c4, c5, c6, c7, c8, c9, Y, Cb, Cr
csc.preset	=	auto, user, rgb, yuvsd, yuvhd
pic.mute	= ? #	on, off
sample.format	= ? #	auto, rgb, 444, 422, 420

Notes

 mcgd.data and tcgd.data allow for MCGD data or user TCGD data to be sent as comma separated x and y co-ordinates in the specified order. Must be preceded by leading 0, e.g. 0.663,0.332.

 mcgd.factory recovers the factory set MCGD values.

 gamut cannot be used as a get-type command. Once a gamut has been set, use *tcgd.data ? to query the values.

 Adjusting the brightness value will reset red.lift, green.lift and blue.lift to zero.

 Adjusting the contrast value will reset red.gain, green.gain and blue.gain to zero.

Geometry

<command>	<operator>	<value>
blanking.top	= ? + - #	0 to 500 (integer)
blanking.bottom	= ? + - #	0 to 500 (integer)
blanking.left	= ? + - #	0 to 500 (integer)
blanking.right	= ? + - #	0 to 500 (integer)
blanking.coordinates	= ? #	ulx, uly, lrx, lry

3D

<command>	<operator>	<values>
3d.enable	= ?	On, off
3d.format	= ?	off – turn 3D off auto – the system will decide the best setting based on the incoming signal, if possible seq – sequential tab – top-and-bottom sbs – side-by-side (half) fpack – frame packing dplr – dual pipe left/right dpew – dual pipe east/west
3d.frmultiplier	= ? + -	1 = x1, 2 = x2, 3 = x3
3d.darktime	= ? + -	0 to 8000, steps of 50 (in μ s)
3d.syncoffset	= ? + -	-1500 to 1500, steps of 100
3d.syncinpolarity	= ?	pos, neg
3d.syncoutpolarity	= ?	pos, neg
3d.syncoutenable	= ?	on, off
3d.dominance	= ?	left, right

Notes

Lamps / Lasers

<command>	<operator>	<values>
laser1.hours laser2.hours lamp1.hours lamp2.hours lamp3.hours lamp4.hours	?	
laser1.strikes laser2.strikes lamp1.strikes lamp2.strikes lamp3.strikes lamp4.strikes	?	
laser1.serial laser2.serial lamp1.serial lamp2.serial lamp3.serial lamp4.serial	?	
laser.power lamp.power	= ?	1 to 100 (integer)

Notes

For projectors with lamp and LED light sources, use lamp in the command (lamp1 to lamp4 for Quad, lamp1 and lamp2 for Dual LED). For laser projectors, replace with laser.



The lampX.hours command (where X is the lamp number) returns the lamp hours in HH:MM format.



Depending on the projector model, the lamp.power command has a different value range as follows:

- For **INSIGHT 4K Dual Laser**, the range is between 30 and 100. Any value lower than 30 will be interpreted as 30 by the projector.
- For **INSIGHT 4K Quad**, the range is between 80 and 100. Any value lower than 80 will be interpreted as 80 by the projector.
- For **INSIGHT 4K Dual LED**, lamp power cannot be changed.

Network

<command>	<operator>	<values>
lan.ip	= ?	xxx.xxx.xxx.xxx
lan.dhcp	= ?	on, off
lan.subnet	= ?	xxx.xxx.xxx.xxx

System

<command>	<operator>	<values>
orientation	= ? #	0 = Desktop Front 1 = Ceiling Front 2 = Desktop Rear 3 = Ceiling Rear
shutter	= ?	on or open off or close
ir.address	= ?	0 to 255
power	= ?	on, off
factory.reset	(execute)	
identify	(execute)	
ir.enable	= ? #	on, off
ir.key	=	0 to 127
convergence	= ? #	redX, greenX, blueX, redY, greenY, blueY (each parameter ranges from 0 to 3)

Notes

 The lan.ip command can only be set if lan.dhcp is set to off.

 Do not set the third octet to 254. You will be unable to control the projector with this setting.

 factory.reset takes a long time to execute. 'ack' is returned when it finishes.

 identify flashes the keypad lights for 10 seconds to identify the projector.

 ir.enable always defaults to on after a power cycle.

 For ir.key see [Keypad and remote control keycode table](#) on the next page.

Keypad and remote control keycode table

KEY_POWER_ON	= 120
KEY_POWER_OFF	= 121
KEY_SHUTTER_OPEN	= 2
KEY_SHUTTER_CLOSE	= 5
KEY_MENU	= 9
KEY_EXIT	= 40
KEY_UP	= 11
KEY_LEFT	= 18
KEY_RIGHT	= 26
KEY_DOWN	= 33
KEY_OK	= 25
KEY_INPUT_PLUS	= 10
KEY_INPUT_MINUS	= 41
KEY_0	= 82
KEY_1	= 42
KEY_2	= 46
KEY_3	= 50
KEY_4	= 55
KEY_5	= 59
KEY_6	= 63
KEY_7	= 68
KEY_8	= 72
KEY_9	= 76
KEY_10_PLUS	= 81
KEY OSD ON	= 1
KEY OSD OFF	= 4
KEY_CONTROL	= 6
KEY_AUTO	= 7
KEY_INFO	= 8
KEY_TEST	= 87
KEY_BRIGHTNESS	= 88
KEY_CONTRAST	= 89
KEY_GAMMA	= 109
KEY_RED	= 54

KEY_GREEN	= 67
KEY_BLUE	= 80
KEY_3D_ON_OFF	= 110
KEY_3D_EYE_SWAP	= 111
KEY_PIP_ON_OFF	= 112
KEY_MAIN_PIP_SWAP	= 113
KEY_UP_FOCUS	= 12
KEY_LEFT_FOCUS	= 19
KEY_RIGHT_FOCUS	= 27
KEY_DOWN_FOCUS	= 34
KEY_UP_SHIFT	= 13
KEY_LEFT_SHIFT	= 20
KEY_RIGHT_SHIFT	= 28
KEY_DOWN_SHIFT	= 35
KEY_UP_ZOOM	= 14
KEY_LEFT_ZOOM	= 21
KEY_RIGHT_ZOOM	= 29
KEY_DOWN_ZOOM	= 36
KEY_UP_ROLL	= 15
KEY_LEFT_ROLL	= 22
KEY_RIGHT_ROLL	= 30
KEY_DOWN_ROLL	= 37
KEY_UP_PITCH	= 16
KEY_LEFT_PITCH	= 23
KEY_RIGHT_PITCH	= 31
KEY_DOWN_PITCH	= 38
KEY_UP_YAW	= 17
KEY_LEFT_YAW	= 24
KEY_RIGHT_YAW	= 32
KEY_DOWN_YAW	= 39
KEY_0_LOAD	= 83
KEY_0_SAVE	= 84
KEY_0_ALT	= 85
KEY_1_LOAD	= 43

KEY_1_SAVE	= 44
KEY_1_ALT	= 45
KEY_2_LOAD	= 47
KEY_2_SAVE	= 48
KEY_2_ALT	= 49
KEY_3_LOAD	= 51
KEY_3_SAVE	= 52
KEY_3_ALT	= 53
KEY_4_LOAD	= 56
KEY_4_SAVE	= 57
KEY_4_ALT	= 58
KEY_5_LOAD	= 60
KEY_5_SAVE	= 61
KEY_5_ALT	= 62
KEY_6_LOAD	= 64
KEY_6_SAVE	= 65
KEY_6_ALT	= 66
KEY_7_LOAD	= 69
KEY_7_SAVE	= 70
KEY_7_ALT	= 71
KEY_8_LOAD	= 73
KEY_8_SAVE	= 74
KEY_8_ALT	= 75
KEY_9_LOAD	= 77
KEY_9_SAVE	= 78
KEY_9_ALT	= 79
KEY_10_PLUS_LOAD	= 101
KEY_10_PLUS_SAVE	= 107
KEY_HASH	= 86
KEY_HASH_LOAD	= 102
KEY_HASH_SAVE	= 108

Notes

Key assignments through
ir.key can be used with custom
applications.

OSD

<command>	<operator>	<values>
osd.enable	= ? #	on, off
osd.position	= ? #	0 to 9
osd.timeout	= ? #	0 to 120 (seconds)
osd.notifications	= ? #	on, off
osd.inputsource	= ? #	on, off
osd.version	?	
osd.zoom	= ? #	on, off
osd.pin	= ? #	0000 to 9999, the default is 1234
osd.pin.reset	(execute)	
osd.pin.enable	= ? #	on, off

Notes

 OSD commands are available only where an OSD option is fitted.

 When osd.timeout is set to a value of 0, the OSD will never time out.

 The osd.pin is used as a security measure on the web. Applies to served OSD only.

Information

<command>	<operator>	<values>
sw.version	?	
board.id	?	
videoboard.id	?	
fw.version	?	
from.version	?	
lens.version	?	
seq.version	?	
model.name	?	
serial	?	
videosw.version	?	
standby.hours	?	
power.cycles	?	
inlet.temp	?	
dmd.temp	?	
laser.module.temp	?	

Notes

- sw.version *returns the software release version.*
- board.id *returns the CPU hardware version.*
- videoboard.id *returns the video hardware version.*
- fw.version *returns the firmware version.*
- from.version *returns the factory ROM version.*
- lens.version *returns the lens mount version.*
- seq.version *returns the formatter sequences version.*
- model.name *returns the projector model name.*
- serial *returns the projector serial number.*
- videosw.version *returns the software release version of the video processor.*
- standby.hours *returns the total number of hours spent on standby.*
- power.cycles *returns the number of times the projector has been switched on at the mains inlet.*
- inlet.temp, laser.module.temp and dmd.temp *return temperature readings at the air inlet, DMD and laser module respectively.*

DIGITAL PROJECTION

INSIGHT 4K Laser Series

High Brightness Digital Video Projector

► PROTOCOL GUIDE



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Introduction**Network Port setup**

- IP address assigned by user
- Port 43728

Notes**Serial Port setup**

- Baud rate 38,400 bps
- Data length 8 bits
- Stop bits one
- Parity none
- Flow control none

Command structure

Byte	Description	Comments
0	Command One (1)	First level commands
1	Command Two (2)	Second level commands
2	Command Three (3)	Third level commands
3	Length (MSB)	Number of bytes of command data
4	Length (LSB)	Number of bytes of command data
5 ... n	Command Data 0 ... n	
n + 1	Checksum	The LSB of the sum of all preceding bytes

In this section bytes are shown separated for clarity: each string is placed in a table where each byte occupies a separate cell.

All values are in hexadecimal format unless explicitly stated otherwise.

Checksum must be correctly calculated. The projector does not respond to an incorrect checksum.

Command example: Laser On

Byte	Value	Description
0	03	Command 1
1	2f	Command 2
2	00	Command 3
3	00	Length (MSB)
4	02	Length (LSB)
5	12	Data
6	01	
7	47	Checksum (see Example 1 in the note for calculation)

The control system should wait for the full response to a command before transmitting the next command.

Notes

If the checksum is greater than 100, then only the least significant byte shall be sent.

Example 1

The **Laser On** command looks like this:

03 2f 00 00 02 12 01 **47**,

where the checksum 47 is obtained by adding up all preceding bytes:

$$3 + 2f + 0 + 0 + 2 + 12 + 1 = 47$$

Example 2

The checksum of the **Set Light Power Level** command with a light power value of 1e (30%) is obtained by adding up all preceding bytes:

$$3 + 10 + 0 + 0 + 5 + c1 + ff + 0 + 1e + 0 = \textbf{1f6}$$

The checksum **1f6** contains more than one byte, therefore only the LSB will be sent with the command:

03 10 00 00 05 c1 ff 00 1e 00 **f6**

Similarly, if the light power value is 64 (100%), the checksum will be **23c** and the actual command will look like this:

03 10 00 00 05 c1 ff 00 64 00 **3c**

Protocol Commands**Control commands****Power On****Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Checksum
02	00	00	00	00	02

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Checksum
22	00	00	c0	00	e2

Notes

Power Off**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Checksum
02	01	00	00	00	03

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Checksum
22	01	00	c0	00	e3

Notes

Light On**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
03	2f	00	00	02	12 01	47

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data 1	Data 2	Checksum
23	2f	00	c0	02	12	00	26

Notes

Light Off**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
03	2f	00	00	02	12	02

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data 1	Data 2	Checksum
23	2f	00	c0	02	12	00	26

Notes

Set Light Power Level**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Light Power Level	Checksum
03	10	00	00	05	c1 ff 00	1e 00	f6

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data 1	Data 2	Checksum
23	10	00	c0	02	00	00	f5

Notes

Light Power Level is represented as a percentage between 30% and 100% (in hex), as in the following examples:

1e = 30 decimal

63 = 99 decimal

64 = 100 decimal

Change the byte in bold and recalculate the checksum.

Get Light Power Level**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data			Checksum
03	05	00	00	03	c1	00	00	cc

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Response Data												Checksum	
23	05	00	c0	10	02	64	00	1e	00	00	00	63	00	07	00	01	00	e5

Notes

Light Power Level is represented as a percentage between 30% and 100% (in hex), as in the following examples:

1e = 30 decimal

63 = 99 decimal

64 = 100 decimal

Get Light Status**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
03	2f	00	00	01	1e	51

Response (example)

Response Data															Checksum					
Response 1	Response 2	Response 3	Response 4	Length	Light Hours	Light Warning Time	Light % Remaining	Light Strike Count												
23	2f	00	c0	0f	1e	42	00	20	4e	64	47	00	00	00	20	4e	64	00	00	6c

Notes

Light Hours: 0042 = 66 hours

Light Warning Time: 4e20 = 20,000 hours

Light % Remaining: 64 = 100%

Light Strike Count: 0047 = 71 strikes

Douser Close**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Checksum
02	16	00	00	00	18

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Checksum
22	16	00	c0	00	f8

Notes

Douser Open**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Checksum
02	17	00	00	00	19

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Checksum
22	17	00	c0	00	f9

Notes

Douser Status**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
00	85	00	00	01	03	89

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data 1	Data 2	Data 3	Data 4	Data 5	Data 6	Data 7	Data 8	Data 9	Data 10	Data 11	Data 12	Data 13	Data 14	Data 15	Data 16	Checksum
20	85	00	c0	10	81	00	00	00	00	00	00	00	00	ff	ff	ff	ff	ff	ff	f0	

Notes

In the **Douser Status** response:

81 = Douser closed
00 = Douser open

Running Status**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
00	85	00	00	01	01	87

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Response Data							Checksum						
External Control	Power	Light Cooling Status	Power Processing	Projector Status / Mode	Light Status	Light On / Off Status												
20	85	00	c0	10	00	00	01	00	00	0c	00	00	ff	00	00	00	00	81

Notes**External Control:**

00 = Off, 01 = On

Power:

00 = Off, 01 = On

Light Cooling Status:

00 = Normal, 01 = On

Power Processing:

00 = Normal

01 = Powering up or down

Projector Status / Mode:

00 = Standby

01 = Power on protect

02 = Ignition first attempt

03 = Power on running

04 = Running: power on, light on

05 = Cooling

06 = ----- (reserved)

07 = Reset wait

08 = Fan stop error

09 = Light ignition retry

0a = Light error

0c = Running: power on, light off

Light Status:

00 = Off, 01 = On

Light On / Off Status:

00 = Normal

01 = Powering up or down

Lens commands**Move Up****Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	03	7f

9e

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Move Down**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	03	81

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Stop Up/Down Movement**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	03	00

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Move Left**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	02	81

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Move Right**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	02 7f	9d

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Stop Left/Right Movement**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	02	00

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Zoom In**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	00 7f	9b

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Zoom Out**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	00 81	9d

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Stop Zoom**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	00	1c

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Focus In**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	01 7f	9c

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Focus Out**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	01	81

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Stop Focus**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	18	00	00	02	01	00

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	18	00	c0	01	00	fb

Notes

Lens Memory commands**Store Position****Send**

Command 1	Command 2	Command 3	Command Data 1					Memory Number	Command 4	Command Data 2					Command Data 3					Memory Number	Command Data 4					Command Data 5					Checksum
03	b1	00	00	42	ee	00	01	00	...	00	6d	65	6d	6f	72	79	20	30	00	...	00	ff	...	ff	ba						

Response (example)

Response 1	Response 2	Response 3	Response Data 1					Memory Number	Response 4	Response 5	Checksum
23	b1	00	c0	04	ee	00	01	00	87		

Notes

 The first **Memory Number** byte will accept a value between 00 and 09.

 The second **Memory Number** byte will accept a value between 30 and 39.

 **Command Data 2** contains thirteen identical 00 bytes.

 **Command Data 4** contains twenty-two identical 00 bytes.

 **Command Data 5** contains twenty identical ff bytes.

Recall Position**Send**

Command 1	Command 2	Command 3	Command Data 1			Memory Number	Command 4	Command Data 2			Command Data 3						Memory Number	Command Data 4			Command Data 5			Checksum	
03	b1	00	00	42	ee	00	02	00	...	00	6d	65	6d	6f	72	79	20	30	00	...	00	ff	...	ff	bb

Response (example)

Response 1	Response 2	Response 3	Response Data 1			Memory Number	Response 4	Response 5	Checksum
23	b1	00	c0	04	ee	00	02	00	88

Notes

 The first **Memory Number** byte will accept a value between 00 and 09.

 The second **Memory Number** byte will accept a value between 30 and 39.

 **Command Data 2** contains thirteen identical 00 bytes.

 **Command Data 4** contains twenty-two identical 00 bytes.

 **Command Data 5** contains twenty identical ff bytes.

Delete Position**Send**

Command 1	Command 2	Command 3	Command Data 1			Memory Number	Command 4	Command Data 2			Command Data 3						Memory Number	Command Data 4			Command Data 5			Checksum
03	b1	00	00	42	ee	00	00	00	...	00	6d	65	6d	6f	72	79	20	30	00	00	ff	...	ff	b9

Response (example)

Response 1	Response 2	Response 3	Response Data 1			Memory Number	Response 4	Response 5	Checksum
23	b1	00	c0	04	ee	00	00	00	86

Notes

 The first **Memory Number** byte will accept a value between 00 and 09.

 The second **Memory Number** byte will accept a value between 30 and 39.

 **Command Data 2** contains thirteen identical 00 bytes.

 **Command Data 4** contains twenty-two identical 00 bytes.

 **Command Data 5** contains twenty identical ff bytes.

Title selection commands (Preset buttons)**Set Title****Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Title Number	Command Data	Checksum
02	03	00	00	02	06	00	0d

Response (example)

Response 1	Response 2	Response 3	Response 4	Length	Data	Checksum
22	03	00	c0	01	00	e6

Notes

 **Title number:** 00 to 63 (i.e. between 0 and 99 decimal).

 Title count in the protocol begins from 00. To set the correct title number, convert the decimal value to hex and then decrease the result by 1. For example, if you want to set title 12, send a value of 0b, the hex equivalent of (decimal) 11.

Get Current Title**Send**

Command 1	Command 2	Command 3	Length MSB	Length LSB	Command Data	Checksum
02	85	00	00	01	02	88

Response (example)

Response Data																	
Response 1	Response 2	Response 3	Response 4	Length	Title Number	04	0d	02	00	00	00	ff	00	00	00	00	95
20	85	00	c0	10	00	0e	04	0d	02	00	00	00	ff	00	00	00	95

Notes

 **Title number:** 00 to 63 (i.e. between 0 and 99 decimal).

 Title count in the protocol begins from 00. To get the real title number, convert the protocol value to decimal and then increase the result by 1. For example, if **Get Current Title** returns a value of 0e (14 in decimal), the current title is 15.

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